

# Coinductive Logic Programming and its Applications

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# Circular Phenomena in Comp. Sci.

- Circularity has dogged Mathematics and Computer Science ever since Set Theory was first developed:
  - The well known Russell's Paradox:
    - $R = \{ x \mid x \text{ is a set that does not contain itself} \}$   
Is R contained in R? Yes and No
  - Liar Paradox: I am a liar
  - Hypergame paradox (Zwicker & Smullyan)
- All these paradoxes involve self-reference through some type of negation
- Russell put the blame squarely on circularity and sought to ban it from scientific discourse:
  - “Whatever involves all of the collection must not be one of the collection”  
-- Russell 1908

# Circularity in Computer Science

- Following Russell's lead, Tarski proposed to ban self-referential sentences in a language
- Rather, have a hierarchy of languages
- All this changed with Kripke's paper in 1975 who showed that circular phenomenon are far more common and circularity can't simply be banned.
- Circularity has been banned from automated theorem proving and logic programming through the occurs check rule:
  - An unbound variable cannot be unified with a term containing that variable
- What if we allowed such unification to proceed (as LP systems always did for efficiency reasons)?

# Circularity in Computer Science

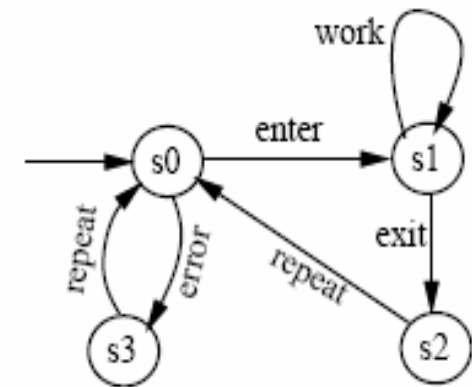
- If occurs check is removed, we'll generate circular (infinite) structures:
  - $X = [1,2,3 | X]$
- Such structures, of course, arise in computing (circular linked lists), but banned in logic/LP.
- Subsequent LP systems did allow for such circular structures (rational terms), but they only exist as data-structures, there is no proof theory to go along with it.
  - One can hold the data-structure in memory within an LP execution, but one can't reason about it.

# Circularity in Everyday Life

- Circularity arises in every day life
  - Most natural phenomenon are cyclical
    - Cyclical movement of the earth, moon, etc.
    - Our digestive system works in cycles
  - Social interactions are cyclical:
    - Conversation = (1<sup>st</sup> speaker, (2<sup>nd</sup> Speaker, Conversation)
    - Shared conventions are cyclical concepts
- Numerous other examples can be found elsewhere (Barwise & Moss 1996)

# Circularity in Computer Science

- Circular phenomenon are quite common in Computer Science:
  - Circular linked lists
  - Graphs (with cycles)
  - Controllers (run forever)
  - Bisimilarity
  - Interactive systems
  - Automata over infinite strings/Kripke structures
  - Perpetual processes
- Logic/LP not equipped to model circularity



# Coinduction

- Circular structures are infinite structures
  - $X = [1, 2 \mid X]$  is logically speaking  $X = [1, 2, 1, 2, \dots]$
- Proofs about their properties are infinite-sized
- *Coinduction* is the technique for proving these properties
  - first proposed by Peter Aczel in the 80s
- Systematic presentation of coinduction & its application to computing, math. and set theory:
  - “Vicious Circles” by Moss and Barwise (1996)
- Our focus: inclusion of coinductive reasoning techniques into LP and theorem proving

# Induction vs Coinduction

- Induction is a mathematical technique for finitely reasoning about an infinite (countable) no. of things.
- Examples of inductive structures:
  - Naturals: 0, 1, 2, ...
  - Lists: [], [X], [X, X], [X, X, X], ...
- 3 components of an inductive definition:
  - (1) Initiality, (2) iteration, (3) minimality
  - for example, the set of lists is specified as follows:
    - [ ] – an empty list is a list (**initiality**)
    - [H | T] is a list if T is a list and H is an element (**iteration**)
    - nothing else is a list (**minimality**)



# Induction vs Coinduction

- Coinduction is a mathematical technique for (finitely) reasoning about infinite things.
  - Mathematical dual of induction
  - If all things were finite, then coinduction would not be needed.
  - Perpetual programs, automata over infinite strings
- 2 components of a coinductive definition:
  - (1) iteration, (2) maximality
    - for example, for a list:  
[ H | T ] is a list if T is a list and H is an element (iteration).  
Maximal set that satisfies the specification of a list.
    - This coinductive interpretation specifies all infinite sized lists

# Example: Natural Numbers

- $\Gamma_N(S) = \{ 0 \} \cup \{ \text{succ}(x) \mid x \in S \}$
- $N = \mu\Gamma_N$ 
  - where  $\mu\Gamma$  is least fixed-point.
- aka “inductive definition”
  - Let  $N$  be the smallest set such that
    - $0 \in N$
    - $x \in N$  implies  $x + 1 \in N$
- Induction corresponds to Least Fix Point (LFP) interpretation.

## Example: Natural Numbers and Infinity

- $\Gamma_N(S) = \{ 0 \} \cup \{ \text{succ}(x) \mid x \in S \}$
- $\Gamma_N$  unambiguously defines another set
- $N' = \nu\Gamma_N = \mathbb{N} \cup \{ \omega \}$ 
  - $\omega = \text{succ}(\text{succ}(\text{succ}(\dots))) = \text{succ}(\omega) = \omega + 1$
  - where  $\nu\Gamma_N$  is a greatest fixed-point
- Coinduction corresponds to Greatest Fixed Point (GFP) interpretation.

# Mathematical Foundations

- Duality provides a source of new mathematical tools that reflect the sophistication of tried and true techniques.

Definition	Proof	Mapping
Least fixed point	Induction	Recursion
Greatest fixed point	Coinduction	Corecursion

- Co-recursion: recursive def'n without a base case

# Applications of Coinduction

- model checking
- bisimilarity proofs
- lazy evaluation in FP
- reasoning with infinite structures
- perpetual processes
- cyclic structures
- operational semantics of “coinductive logic programming”
- Type inference systems for lazy functional languages

# Inductive Logic Programming

- Logic Programming
  - is actually inductive logic programming.
  - has inductive definition.
  - useful for writing programs for reasoning about finite things:
    - data structures
    - properties

# Infinite Objects and Properties

- Traditional logic programming is unable to reason about infinite objects and/or properties.
- (The glass is only half-full)
- Example: perpetual binary streams
  - traditional logic programming cannot handle

bit(0).

bit(1).

bitstream( [ H | T ] ) :- bit( H ), bitstream( T ).

!?- X = [ 0, 1, 1, 0 | X ], bitstream( X ).

- Goal: Combine traditional LP with coinductive LP

# Overview of Coinductive LP

- Coinductive Logic Program is
  - a definite program with maximal co-Herbrand model declarative semantics.
- Declarative Semantics: across the board dual of traditional LP:
  - greatest fixed-points
  - terms: co-Herbrand universe  $U^{\text{co}}(P)$
  - atoms: co-Herbrand base  $B^{\text{co}}(P)$
  - program semantics: maximal co-Herbrand model  $M^{\text{co}}(P)$ .



# Coinductive LP: An Example

- Let  $P_1$  be the following coinductive program.
    - $\text{:- coinductive from/2.}$   $\text{from}(x) = x \text{ cons from}(x+1)$
    - $\text{from}( N, [ N | T ] ) \text{ :- from}( s(N), T ).$
    - $! \text{?- from}( 0, X ).$
  - co-Herbrand Universe:  $U^{\text{co}}(P_1) = N \cup \Omega \cup L$  where
    - $N = [0, s(0), s(s(0)), \dots]$ ,  $\Omega = \{ s(s(s(\dots))) \}$ , and  $L$  is the set of all finite and infinite lists of elements in  $N$ ,  $\Omega$  and  $L$ .
  - co-Herbrand Model:
    - $M^{\text{co}}(P_1) = \{ \text{from}(t, [t, s(t), s(s(t)), \dots]) \mid t \in U^{\text{co}}(P_1) \}$
  - $\text{from}(0, [0, s(0), s(s(0)), \dots]) \in M^{\text{co}}(P_1)$  implies the query holds
  - Without “coinductive” declaration of  $\text{from}$ ,  $M^{\text{co}}(P_1) = \emptyset$
- This corresponds to traditional semantics of LP with infinite trees.

# Operational Semantics: co-SLD

- nondeterministic state transition system
- states are pairs of
  - a finite list of syntactic atoms [resolvent] (as in Prolog)
  - a set of syntactic term equations of the form  $x = f(x)$  or  $x = t$ 
    - For a program  $p :- p. \Rightarrow$  the query  $|- p.$  will succeed.
    - $p([1 | T]) :- p(T). \Rightarrow$   $|- p(X)$  to succeed with  $X = [1 | X]$ .
- transition rules
  - definite clause rule
  - “coinductive hypothesis rule”
    - if a coinductive goal  $Q$  is called,  
and  $Q$  unifies with a call made earlier (e.g.,  $P :- Q$ )  
then  $Q$  succeeds.

# Correctness

- Theorem (soundness). If atom  $A$  has a successful co-SLD derivation in program  $P$ , then  $E(A)$  is true in program  $P$ , where  $E$  is the resulting variable bindings for the derivation.
- Theorem (completeness). If  $A \in M^{\text{co}}(P)$  has a rational proof, then  $A$  has a successful co-  
SLD derivation in program  $P$ .
  - Completeness only for rational/regular proofs

# Implementation

- Search strategy: hypothesis-first, leftmost, depth-first
- Meta-Interpreter implementation.

```
query(Goal) :- solve([],Goal).
```

```
solve(Hypothesis, (Goal1,Goal2)) :-
```

```
    solve( Hypothesis, Goal1), solve(Hypothesis,Goal2).
```

```
solve( _ , Atom) :- builtin(Atom), Atom.
```

```
solve(Hypothesis,Atom):- member(Atom, Hypothesis).
```

```
solve(Hypothesis,Atom):- notbuiltin(Atom),
```

```
    clause(Atom,Atoms),
```

```
    solve([Atom|Hypothesis],Atoms).
```

- A more efficient implem. atop YAP also available

# Example: Number Stream

$\text{:- coinductive stream/1.}$

$\text{stream( [ H | T ] ) :- num( H ), stream( T ).}$

$\text{num( 0 ).}$

$\text{num( s( N ) ) :- num( N ).}$

$[\text{?- stream( [ 0, s( 0 ), s( s( 0 ) ) | T ] ).}$

1. MEMO:  $\text{stream( [ 0, s( 0 ), s( s( 0 ) ) | T ] )}$

2. MEMO:  $\text{stream( [ s( 0 ), s( s( 0 ) ) | T ] )}$

3. MEMO:  $\text{stream( [ s( s( 0 ) ) | T ] )}$

Answers:

$T = [ 0, s(0), s(s(0)), s(s(0)) | T ]$

$T = [ 0, s(0), s(s(0)), s(0), s(s(0)) | T ]$

$T = [ 0, s(0), s(s(0)) | T ] \dots$

$T = [ 0, s(0), s(s(0)) | X ]$  (where X is any rational list of numbers.)

# Example: Append

`:- coinductive append/3.`

`append( [], X, X ).`

`append( [ H | T ], Y, [ H | Z ] ) :- append( T, Y, Z ).`

`|?- Y = [ 4, 5, 6 | Y ], append( [ 1, 2, 3 ], Y, Z).`

Answer: `Z = [ 1, 2, 3 | Y ], Y = [ 4, 5, 6 | Y ]`

`|?- X = [ 1, 2, 3 | X ], Y = [ 3, 4 | Y ], append( X, Y, Z).`

Answer: `Z = [ 1, 2, 3 | Z ].`

`|?- Z = [ 1, 2 | Z ], append( X, Y, Z ).`

Answer: `X = [], Y = [ 1, 2 | Z ];`      `X = [ 1, 2 | X ], Y = _`

`X = [ 1 ], Y = [ 2 | Z ];`

`X = [ 1, 2 ], Y = Z; .... ad infinitum`

# Example: Comember

member(H, [ H | T ]).

member(H, [ X | T ]) :- member(H, T).

?- L = [1,2 | L], member(3, L) succeeds. Instead:

:- coinductive comember/2. %drop/3 is inductive

comember(X, L) :- drop(X, L, R), comember(X, R).

drop(H, [ H | T ], T).

drop(H, [ X | T ], T1) :- drop(H, T, T1).

?- X=[ 1, 2, 3 | X ], comember(2,X).

Answer: yes.

?- X=[ 1, 2, 3, 1, 2, 3 ], comember(2, X).

Answer: no.

?- X=[1, 2, 3 | X], comember(Y, X).

Answer: Y = 1;

Y = 2;

Y = 3;

?- X = [1,2 | X], comember(3, X).

Answer: no

# Example: Sieve of Eratosthenes

- Lazy evaluation can be elegantly incorporated in LP

`:- coinductive sieve/2, filter/3, comember/2.`

`primes(X) :- generate_infinite_list(I),sieve(I,L),comember(X,L).`

`sieve([H|T],[H,R]) :- filter(H,T,F),sieve(F,R).`

`filter(H,[ ],[ ]).`

`filter(H,[K | T],[K | T1]):- R is K mod H, R>0,filter(H,T,T1).`

`filter(H,[K | T],T1) :- 0 is K mod H, filter(H,T,T1).`

`:-coinductive int/2`

`int(X,[X | Y]) :- X1 is X+1, int(X1,Y).`

`generate_infinite_list(I) :- int(2,I).`



# Co-Logic Programming

- combines both halves of logic programming:
  - traditional logic programming
  - coinductive logic programming
- syntactically identical to traditional logic programming, except predicates are labeled:
  - Inductive, or
  - coinductive
- and stratification restriction enforced where:
  - inductive and coinductive predicates cannot be mutually recursive. e.g.,  
p :- q.  
q :- p.  
Program rejected, if p coinductive & q inductive
- Implementation on top of YAP available.

# Application: Model Checking

- automated verification of hardware and software systems
- $\omega$ -automata
  - accept infinite strings
  - accepting state must be traversed infinitely often
- requires computation of lfp and gfp
- co-logic programming provides an elegant framework for model checking
- traditional LP works for safety property (that is based on lfp) in an elegant manner, but not for liveness .

# Verification of Properties

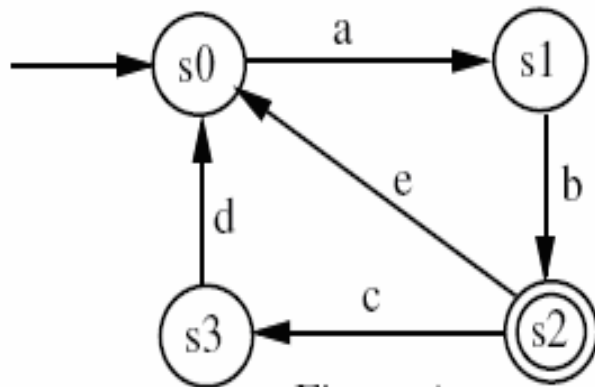


Figure A

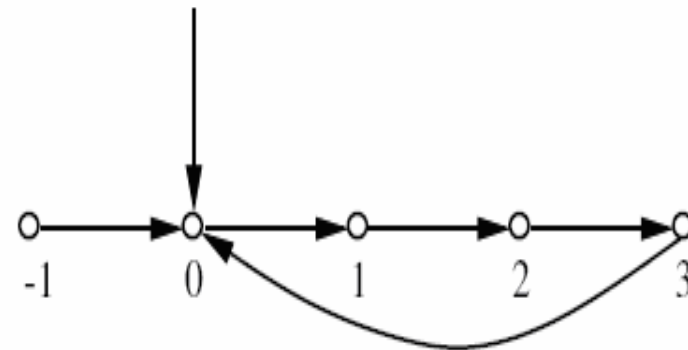


Figure B

- Types of properties: safety and liveness
- Search for counter-example

# Safety versus Liveness

- Safety
  - “nothing bad will happen”
  - naturally described inductively
  - straightforward encoding in traditional LP
- liveness
  - “something good will eventually happen”
  - dual of safety
  - naturally described coinductively
  - straightforward encoding in coinductive LP

# Finite Automata

```
automata([X|T], St):- trans(St, X, NewSt), automata(T, NewSt).
automata([ ], St) :- final(St).
```

```
trans(s0, a, s1).    trans(s1, b, s2).    trans(s2, c, s3).
trans(s3, d, s0).    trans(s2, 3, s0).    final(s2).
```

?- automata(X,s0).

X=[ a, b];

X=[ a, b, e, a, b];

X=[ a, b, e, a, b, e, a, b];

.....

.....

.....

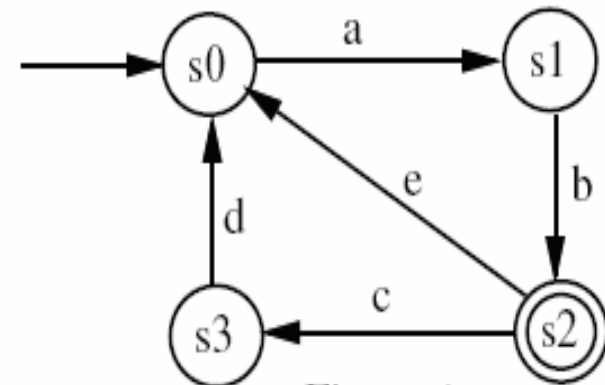


Figure A

# Infinite Automata

```
automata([X|T], St):- trans(St, X, NewSt), automata(T, NewSt).
```

```
trans(s0,a,s1).    trans(s1,b,s2).    trans(s2,c,s3).  
trans(s3,d,s0).    trans(s2,3,s0).    final(s2).
```

?- automata(X,s0).

X=[ a, b, c, d | X ];

X=[ a, b, e | X ];

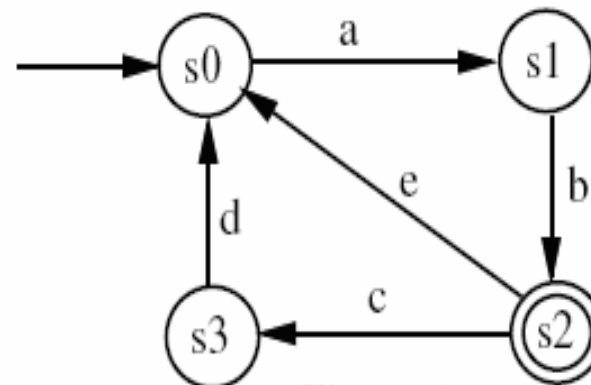


Figure A

# Verifying Liveness Properties

- Verifying safety properties in LP is relatively easy: safety modeled by reachability
- Accomplished via tabled logic programming
- Verifying liveness is much harder: a counterexample to liveness is an infinite trace
- Verifying liveness is transformed into a safety check via use of negations in model checking and tabled LP
  - Considerable overhead incurred
- Co-LP solves the problem more elegantly:
  - Infinite traces that serve as counter-examples are easily produced as answers

# Verifying Liveness Properties

- Consider Safety:
  - Question: Is an unsafe state,  $S_u$ , reachable (safe)?
  - If answer is yes, the path to  $S_u$  is the counter-ex.
- Consider Liveness, then dually
  - Question: Is a state,  $D$ , that should be dead, live?
  - If answer is yes, the infinite path containing  $D$  is the counter example
    - Co-LP will produce this infinite path as the answer
- Checking for liveness is just as easy as checking for safety



# Counter

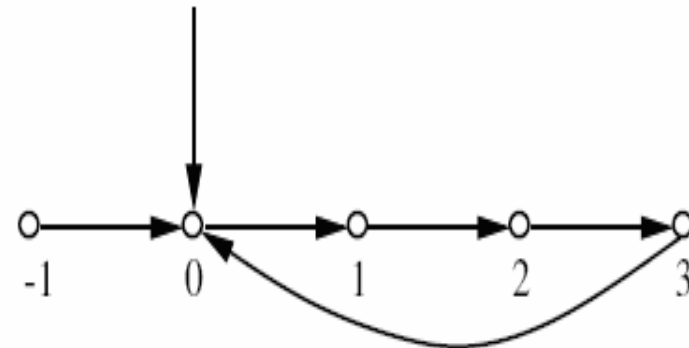


Figure B

$sm1(N,[sm1|T]) :- N1 \text{ is } N+1 \text{ mod } 4, s0(N1,T), N1 \geq 0.$

$s0(N,[s0|T]) :- N1 \text{ is } N+1 \text{ mod } 4, s1(N1,T), N1 \geq 0.$

$s1(N,[s1|T]) :- N1 \text{ is } N+1 \text{ mod } 4, s2(N1,T), N1 \geq 0.$

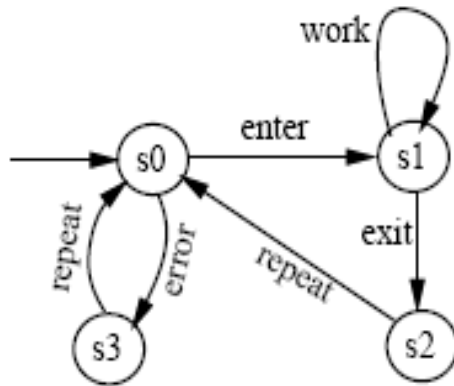
$s2(N,[s2|T]) :- N1 \text{ is } N+1 \text{ mod } 4, s3(N1,T), N1 \geq 0.$

$s3(N,[s3|T]) :- N1 \text{ is } N+1 \text{ mod } 4, s0(N1,T), N1 \geq 0.$

?-  $sm1(-1,X), comember(sm1,X).$

No. (because  $sm1$  does not occur in  $X$  infinitely often).

# Nested Finite and Infinite Automata



`:- coinductive state/2.`

```
state(s0, [s0,s1 | T]):- enter, work,
                        state(s1,T).
```

```
state(s1, [s1 | T]):- exit, state(s2,T).
```

```
state(s2, [s2 | T]):- repeat, state(s0,T).
```

```
state(s0, [s0 | T]):- error, state(s3,T).
```

```
state(s3, [s3 | T]):- repeat, state(s0,T).
```

```
work.    enter. repeat. exit. error.
```

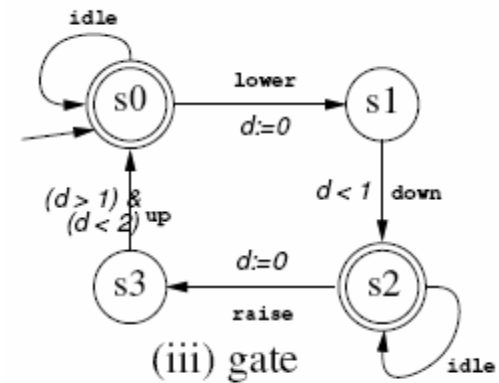
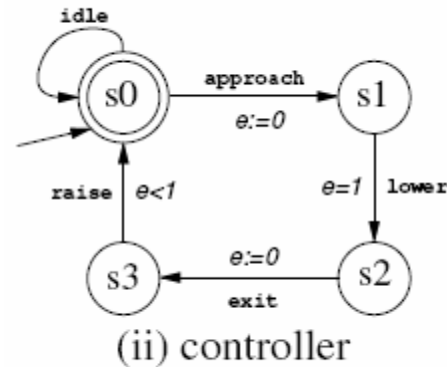
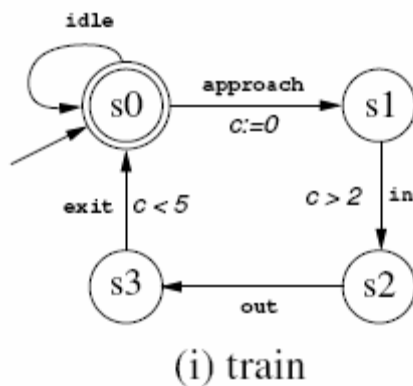
```
work :- work.
```

```
|- state(s0,X), absent(s2,X).
```

```
X=[ s0, s3 | X ]
```

# Verification of Real-Time Systems

## “Train, Controller, Gate”



## Timed Automata

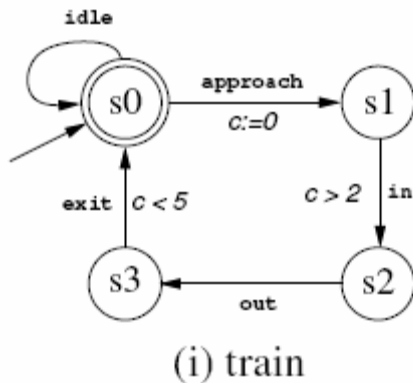
- $\omega$ -automata w/ time constrained transitions & stopwatches
- straightforward encoding into  $CLP(\mathcal{R})$  + Co-LP

# Verification of Real-Time Systems

## “Train, Controller, Gate”

`:- use_module(library(clpr)).`

`:- coinductive driver/9.`



`train(X, up, X, T1, T2, T2). % up=idle`

`train(s0, approach, s1, T1, T2, T3) :- {T3=T1}.`

`train(s1, in, s2, T1, T2, T3) :- {T1-T2 > 2, T3=T2}`

`train(s2, out, s3, T1, T2, T3).`

`train(s3, exit, s0, T1, T2, T3) :- {T3=T2, T1-T2 < 5}.`

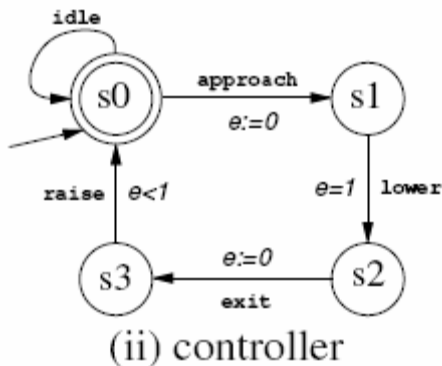
`train(X, lower, X, T1, T2, T2).`

`train(X, down, X, T1, T2, T2).`

`train(X, raise, X, T1, T2, T2).`

# Verification of Real-Time Systems

## “Train, Controller, Gate”



$\text{contr}(s0, \text{approach}, s1, T1, T2, T1).$

$\text{contr}(s1, \text{lower}, s2, T1, T2, T3):- \{T3=T2, T1-T2=1\}.$

$\text{contr}(s2, \text{exit}, s3, T1, T2, T1).$

$\text{contr}(s3, \text{raise}, s0, T1, T2, T2):-\{T1-T2<1\}.$

$\text{contr}(X, \text{in}, X, T1, T2, T2).$

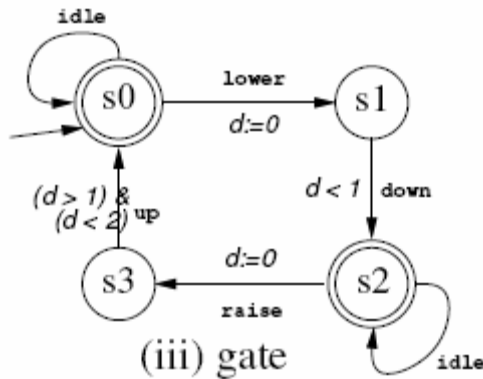
$\text{contr}(X, \text{up}, X, T1, T2, T2).$

$\text{contr}(X, \text{out}, X, T1, T2, T2).$

$\text{contr}(X, \text{down}, X, T1, T2, T2).$

# Verification of Real-Time Systems

## “Train, Controller, Gate”



$\text{gate}(s0, \text{lower}, s1, T1, T2, T3) :- \{T3 = T1\}.$   
 $\text{gate}(s1, \text{down}, s2, T1, T2, T3) :- \{T3 = T2, T1 - T2 < 1\}.$   
 $\text{gate}(s2, \text{raise}, s3, T1, T2, T3) :- \{T3 = T1\}.$   
 $\text{gate}(s3, \text{up}, s0, T1, T2, T3) :- \{T3 = T2, T1 - T2 > 1, T1 - T2 < 2\}.$   
 $\text{gate}(X, \text{approach}, X, T1, T2, T2).$   
 $\text{gate}(X, \text{in}, X, T1, T2, T2).$   
 $\text{gate}(X, \text{out}, X, T1, T2, T2).$   
 $\text{gate}(X, \text{exit}, X, T1, T2, T2).$

# Verification of Real-Time Systems

:- coinductive driver/9.

```
driver(S0,S1,S2, T,T0,T1,T2, [ X | Rest ], [ (X,T) | R ]) :-
    train(S0,X,S00,T,T0,T00),  contr(S1,X,S10,T,T1,T10),
    gate(S2,X,S20,T,T2,T20),  {TA > T},
    driver(S00,S10,S20,TA,T00,T10,T20,Rest,R).
```

[?- driver(s0,s0,s0,T,Ta,Tb,Tc,X,R).

```
R=[(approach,A), (lower,B), (down,C), (in,D), (out,E), (exit,F),
    (raise,G), (up,H) | R ],
```

```
X=[approach, lower, down, in, out, exit, raise, up | X] ;
```

```
R=[(approach,A),(lower,B),(down,C),(in,D),(out,E),(exit,F),(raise,G),
    (approach,H),(up,I)|R],
```

```
X=[approach,lower,down,in,out,exit,raise,approach,up | X] ;
```

% where A, B, C, ... H, I are the corresponding wall clock time of events generated.

# Goal-directed execution of ASP

- Answer set programming (ASP) is a popular formalism for non monotonic reasoning
- Applications in real-world reasoning, planning, etc.
- Semantics given via lfp of a residual program obtained after “Gelfond-Lifschitz” transform
- Popular implementations: Smodels, DLV, etc.
  1. No goal-directed execution strategy available
  2. ASP limited to only finitely groundable programs
- Co-logic programming solves both these problems.
- Also provides a goal-directed method to check if a proposition is true in some model of a prop. formula



# Why Goal-directed ASP?

- Most of the time, given a theory, we are interested in knowing if a *particular* goal is true or not.
- Top down goal-directed execution provides operational semantics (important for usability)
- Execution more efficient.
  - Tabled LP vs bottom up Deductive Databases
- Why check the consistency of the whole knowledgebase?
  - Inconsistency in some unrelated part will scuttle the whole system
- Most practical examples anyway add a constraint to force the answer set to contain a certain goal.
  - E.g. Zebra puzzle:  $\text{:- not } \textit{satisfied}.$
- Answer sets of non-finitely groundable programs computable & Constraints incorporated in Prolog style.

# Negation in Co-LP

- Given a clause such as  
 $p :- q, \text{ not } p.$   
?-  $p.$  fails coinductively when not  $p$  is encountered
- To incorporate negation in coinductive reasoning, need a negative coinductive hypothesis rule:
  - In the process of establishing  $\text{not}(p)$ , if  $\text{not}(p)$  is seen again in the resolvent, then  $\text{not}(p)$  succeeds
- Also,  $\text{not not } p$  reduces to  $p$ .
- Answer set programming makes the “glass completely full” by taking into account failing computations:
  - $p :- q, \text{ not } p.$  is consistent if  $p = \text{false}$  and  $q = \text{false}$
- However, this takes away monotonicity:  $q$  can be constrained to false, causing  $q$  to be withdrawn, if it was established earlier.

# ASP

- Consider the following program, A:  
p :- not q.                    t.        r :- t, s.  
q :- not p.                    s.  
A has 2 answer sets: {p, r, t, s} & {q, r, t, s}.
- Now suppose we add the following rule to A:  
h :- p, not h.        (falsify p)  
Only one answer set remains: {q, r, t, s}
- Gelfond-Lifschitz Method:
  - Given an answer set S, for each  $p \in S$ , delete all rules whose body contains “not p”;
  - delete all goals of the form “not q” in remaining rules
  - Compute the least fix point, L, of the residual program
  - If  $S = L$ , then S is an answer set

# Goal-directed ASP

- Consider the following program, A':
 

p :- not q.	t.	r :- t, s.
q :- not p, r.	s.	h :- p, not h.
- Separate into constraint and non-constraint rules: only 1 constraint rule in this case.
- Execute the query under co-LP, candidate answer sets will be generated.
- Keep the ones not rejected by the constraints.
- Suppose the query is ?- q. Execution:
 

q	→	not p, r									
→	not not q, r	→	q, r	→	r	→	t, s	→	s	→	success.

Ans = {q, r, t, s}
- Next, we need to check that constraint rules will not reject the generated answer set.
  - (it doesn't in this case)

# Goal-directed ASP

- In general, for the constraint rules of  $p$  as head,  $p_1 :- B_1. p_2 :- B_2. \dots p_n :- B_n.$ , generate rule(s) of the form:  
     $chk\_p_1 :- not(p_1), B_1.$   
     $chk\_p_2 :- not(p_2), B_2.$   
    ...  
     $chk\_p_n :- not(p), B_n.$
- Generate:  $nmr\_chk :- not(chk\_p_1), \dots, not(chk\_p_n).$
- For each pred. definition, generate its negative version:  
     $not\_p :- not(B_1), not(B_2), \dots, not(B_n).$
- If you want to ask query  $Q$ , then ask  $?- Q, nmr\_chk.$
- Execution keeps track of atoms in the answer set (PCHS) and atoms not in the answer set (NCHS).

# Goal-directed ASP

- Consider the following program, P1:
  - (i)  $p \text{ :- not } q.$     (ii)  $q \text{ :- not } r.$     (iii)  $r \text{ :- not } p.$     (iv)  $q \text{ :- not } p.$
 P1 has 1 answer set:  $\{q, r\}$ .
- Separate into: 3 constraint rules (i, ii, iii)
  - 2 non-constraint rules (i, iv).

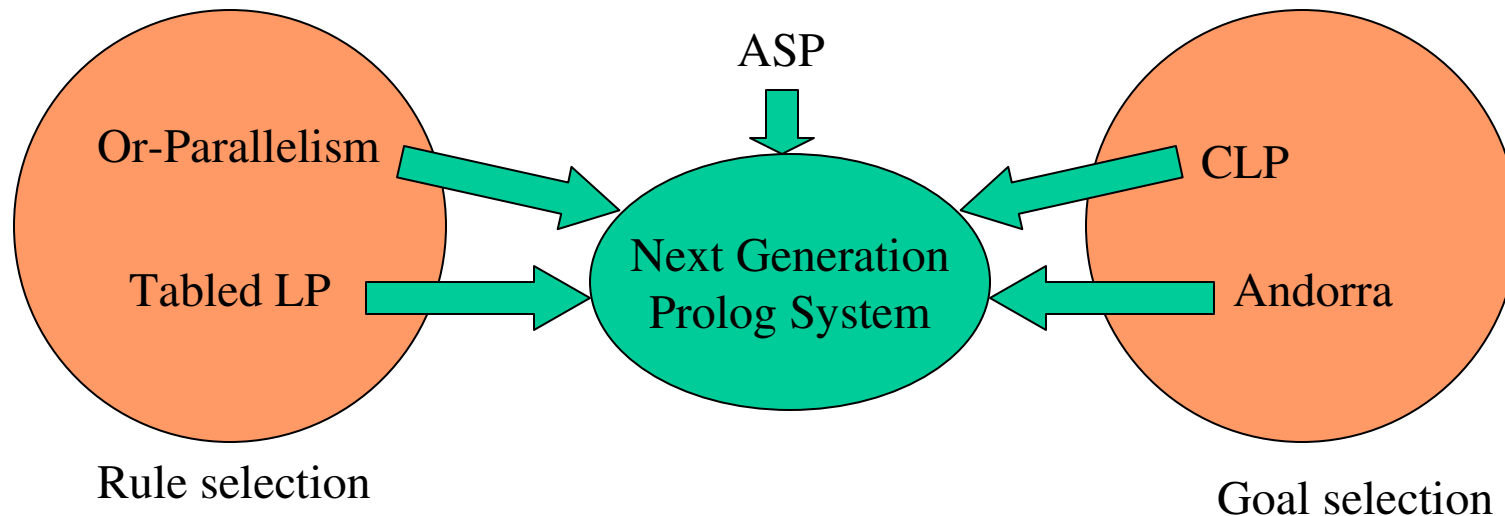
$p \text{ :- not}(q).$      $q \text{ :- not}(r).$      $r \text{ :- not}(p).$      $q \text{ :- not}(p).$   
 $chk\_p \text{ :- not}(p), not(q).$      $chk\_q \text{ :- not}(q), not(r).$      $chk\_r \text{ :- not}(r), not(p).$   
 $nmr\_chk \text{ :- not}(chk\_p), not(chk\_q), not(chk\_r).$   
 $not\_p \text{ :- } q.$      $not\_q \text{ :- } r, p.$      $not\_r \text{ :- } p.$

Suppose the query is  $?- r.$

Expand as in co-LP:  $r \rightarrow not\ p \rightarrow not\ not\ q \rightarrow q ( \rightarrow not\ r \rightarrow fail, backtrack ) \rightarrow not\ p \rightarrow success.$  Ans= $\{r, q\}$  which satisfies the constraint rules of  $nmr\_chk$ .

# Next Generation of LP System

- Lot of research in LP resulting in advances:
  - CLP, Tabled LP, Parallelism, Andorra, ASP, now co-LP
- However, no “one stop shop” system
- Dream: build this “one stop shop” system



# Related Publications

1. L. Simon, A. Mallya, A. Bansal, and G. Gupta. Coinductive logic programming. In *ICLP'06*.
2. L. Simon, A. Bansal, A. Mallya, and G. Gupta. Co-Logic programming: Extending logic programming with coinduction. In *ICALP'07*.
3. ICLP'07 Proceedings (this tutorial)
4. A. Bansal, R. Min, G. Gupta. Goal-directed Execution of ASP. Internal Report, UT Dallas
5. R. Min, A. Bansal, G. Gupta. Goal-directed Execution of ASP with General Predicates. Forthcoming.
6. A. Bansal, R. Min, G. Gupta. Resolution Theorem Proving with Coinduction. Internal Report, UT Dallas



# Conclusion

- Circularity is a common concept in everyday life and computer science:
- Logic/LP is unable to cope with circularity
- Solution: introduce coinduction in Logic/LP
  - dual of traditional logic programming
  - operational semantics for coinduction
  - combining both halves of logic programming
- applications to verification, non monotonic reasoning, negation in LP, web services, theorem proving, propositional satisfiability.
- Acknowledgment.: V. Santos Costa, R. Rocha, F. Silva  
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