

NAME: SOLUTIONS

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MATH 423 (Spring 2004) Exam 1, March 8th

No calculators, books or notes!

Show all work and give complete explanations for all your answers.

This is a 75 minute exam. It is worth a total of 75 points.

7 (1) [15 pts]

- (a) Calculate the 1-form df , for the function $f(x, y) = x^2 + \cos(y)$, and evaluate $df(\vec{v}_p)$, where $p = (2, \pi/2)$, and $\vec{v} = (4, 5)$.

$$df = \frac{\partial f}{\partial x} dx + \frac{\partial f}{\partial y} dy = 2x dx - \sin y dy$$

$$df(\vec{v}_p) = 2 \cdot 2 \cdot 4 - \sin\left(\frac{\pi}{2}\right) 5$$

$$= 16 - 5 = 11$$

- 8 (b) Compute the covariant derivate $\nabla_V W$, of the vector field $W = (xy, x^2 + y^3)$ on \mathbb{R}^2 with respect to the vector field $V = (y, x)$ at the point $p = (2, 3)$.

$$\begin{aligned} \nabla_V W &= \nabla_V (xy, x^2 + y^3) \\ &= (\vec{V}[xy], \vec{V}[x^2 + y^3]) \quad \vec{V}[f] = \nabla f \cdot V \\ &= ((y, 0) \cdot (y, x), (2x, 3y^2) \cdot (y, x)) \\ &= (x^2 + y^2, 2xy + 3xy^2) \end{aligned}$$

$$\begin{aligned} \nabla_V W(2, 3) &= (2^2 + 3^2, 2 \cdot 2 \cdot 3 + 3 \cdot 2 \cdot 3^2) \\ &= (13, 66) \end{aligned}$$

(2) [15 pts] Let $\beta : I \rightarrow \mathbf{R}^3$ be the unit speed curve

$$\beta(s) = (3 \cos(\frac{s}{5}), 3 \sin(\frac{s}{5}), \frac{4}{5}s).$$

10 (a) Compute the Frenet frame and the curvature and torsion of β

$$T = \beta' = \left(-\frac{3}{5} \sin\left(\frac{s}{5}\right), \frac{3}{5} \cos\left(\frac{s}{5}\right), \frac{4}{5} \right)$$

$$T' = \left(-\frac{3}{25} \cos\left(\frac{s}{5}\right), -\frac{3}{25} \sin\left(\frac{s}{5}\right), 0 \right) = \kappa N$$

$$\text{So } \kappa = \|T'\| = \frac{3}{25}$$

$$\boxed{\kappa = \frac{3}{25}}$$

$$N = T'/\kappa = \left(-\cos\left(\frac{s}{5}\right), -\sin\left(\frac{s}{5}\right), 0 \right)$$

$$B = T \times N = \left(\frac{4}{5} \sin \frac{s}{5}, -\frac{4}{5} \cos \frac{s}{5}, \frac{3}{5} \right)$$

$$B' = -\tau N \quad \text{gives us } \tau:$$

$$B' = \left(\frac{4}{25} \cos \frac{s}{5}, \frac{4}{25} \sin \frac{s}{5}, 0 \right) = -\frac{4}{25} N$$

So

$$\boxed{\tau = \frac{4}{25}}$$

 (b) Find the equation of the osculating plane of β at $s = 0$.

NORMAL TO PLANE

$$\vec{n} = B(0) = \left(0, -\frac{4}{5}, \frac{3}{5}\right)$$

POINT IN PLANE

$$\vec{s}_0 = \beta(0) = (3, 0, 0)$$

EQUATION OF PLANE $\vec{s} = (x, y, z)$

$$(\vec{s} - \vec{s}_0) \cdot \vec{n} = 0$$

or

$$4y = 3z$$

(3) [15 pts] Let $\beta : I \rightarrow \mathbf{R}^3$ be a unit speed curve with curvature $\kappa > 0$.

(a) Assuming that T , N , and B are a frame, and that $T' = \kappa N$ and $B' = -\tau N$, prove that

$$N' = -\kappa T + \tau B$$

Since T, N, B form a frame at each point of β and since N' is a vector field along β

$$N' = aT + bN + cB \quad \text{for some functions}$$

a, b, c on I .

Since T, N, B are mutually orthogonal and have length 1

$$N' = (N \cdot T)T + (N \cdot N)N + (N \cdot B)B.$$

Also

$$\textcircled{1} \quad N \cdot T = 0 \Rightarrow N' \cdot T + N \cdot T' = 0 \Rightarrow N' \cdot T = -T' \cdot N \\ = -\kappa N \cdot N$$

$$\textcircled{2} \quad N \cdot N = 0 \Rightarrow N' \cdot N = 0 \Rightarrow N' \cdot N = 0$$

$$\textcircled{3} \quad N \cdot B = 0 \Rightarrow N' \cdot B + N \cdot B' = 0 \Rightarrow N' \cdot B = -N \cdot B' = -\tau N \cdot N = -\tau$$

So $N' = -\kappa T + \tau B$.

(b) Express B'' in terms of T , N , and B .

$$B' = -\tau N$$

$$\text{So } B'' = -(-\tau N)' = -\tau' N - \tau N' \\ = -\tau' N - \tau(-\kappa T + \tau B) \quad \text{by } \textcircled{3}$$

$$B'' = -\tau \kappa T - \tau' N - \tau^2 B$$

(4) [15 pts] One way to define a system of coordinates for the sphere S^2 given by

$$x^2 + y^2 + (z - 1)^2 = 1$$

is to consider the stereographic projection mapping

$$\pi : S^2 \setminus \{N\} \rightarrow \mathbf{R}^2$$

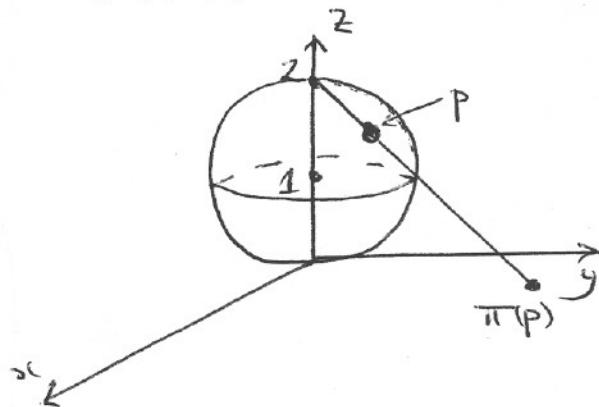
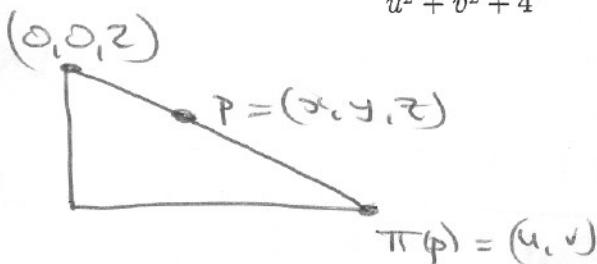
whose domain is the complement of the north pole $N = (0, 0, 2)$ in S^2 . This mapping is defined as follows. Given a point p on $S^2 \setminus \{N\}$, draw a line from the north pole, N , through the point p . The point $\pi(p)$ is the point where this line intersects the plane $z = 0$.

The stereographic coordinate patch is defined to be the function $\mathbf{x} : \mathbf{R}^2 \rightarrow S^2 \setminus \{N\}$ given by the inverse function to π , i.e., $\mathbf{x} = \pi^{-1}$.

If $p = (x, y, z)$ and $\pi(p) = (u, v)$, then we have $\mathbf{x}(u, v) = (x, y, z)$.

(a) Show that

$$x = \frac{4u}{u^2 + v^2 + 4}, \quad y = \frac{4v}{u^2 + v^2 + 4}, \quad z = \frac{2(u^2 + v^2)}{u^2 + v^2 + 4}$$



The line from $(0, 0, 2)$ to (x, y, z) is parametrized by

$$\vec{l}(s) = (0, 0, 2) + s[(x, y, z) - (0, 0, 2)] = (sx, sy, 2 + s(z-2))$$

Find s so that $\vec{l}(s) = (u, v, 0)$:

$$2 + s(z-2) = 0 \Rightarrow s = \frac{2}{2-z}$$

Therefore for this s :

$$x = \frac{u}{s}, \quad y = \frac{v}{s}, \quad z = 2\left(1 - \frac{1}{s}\right)$$

$$\text{But } x^2 + y^2 + (z-1)^2 = 1$$

$$\text{So } 1 = \left(\frac{u}{s}\right)^2 + \left(\frac{v}{s}\right)^2 + \left(1 - \frac{z}{s}\right)^2$$

$$1 = \frac{u^2 + v^2 + (s-z)^2}{s^2}$$

\Rightarrow

$$\boxed{s = \frac{u^2 + v^2 + 4}{4}}$$

So

$$x = \frac{u}{s} = \frac{4u}{u^2 + v^2 + 4} \quad y = \frac{v}{s} = \frac{4v}{u^2 + v^2 + 4}$$

$$z = 2\left(1 - \frac{1}{s}\right) = \frac{2(u^2 + v^2)}{u^2 + v^2 + 4}$$

\checkmark (b) Let $x_* : T_{(u,v)}\mathbb{R}^2 \rightarrow T_{x(u,v)}S^2$ be the tangent map of x . Compute $x_*(w_{(u_0,v_0)})$ where $w = (1,0)$ and $(u_0, v_0) = (1,2)$.

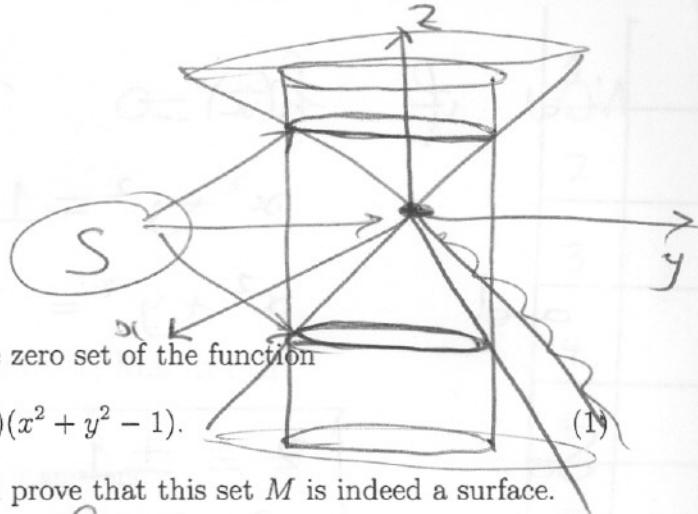
$$\vec{x}_*(\vec{w}_{(1,2)}) = \frac{\partial \vec{x}}{\partial u}(1,2) \quad \text{where } \vec{x} = (x; y, z)$$

Now

$$\frac{\partial \vec{x}}{\partial u} = \begin{pmatrix} \frac{\partial x}{\partial u} \\ \frac{\partial y}{\partial u} \\ \frac{\partial z}{\partial u} \end{pmatrix} = \begin{pmatrix} \frac{4(v^2 - u^2 + 4)}{(u^2 + v^2 + 4)^2} \\ \frac{-8uv}{(u^2 + v^2 + 4)^2} \\ \frac{16u}{(u^2 + v^2 + 4)^2} \end{pmatrix}$$

\checkmark

$$\text{So } \frac{\partial \vec{x}}{\partial u}(1,2) = \left(\frac{28}{81}, -\frac{16}{81}, \frac{16}{81} \right)$$



(5) [15 pts] Let $Z = \{(x, y, z) \in \mathbb{R}^3 \mid f(x, y, z) = 0\}$, be the zero set of the function

$$f(x, y, z) = (x^2 + y^2 - z^2)(x^2 + y^2 - 1).$$

Find the largest subset M of Z so that M is a surface, and prove that this set M is indeed a surface.

Let $g(x, y, z) = x^2 + y^2 - z^2$, $h(x, y, z) = x^2 + y^2 - 1$.

Then $f = gh$

$Z = \text{Zero}(f) = \text{Zero}(g) \cup \text{Zero}(h)$ is the union
of a double cone ($g=0$) and a cylinder ($h=0$).

We must find the points of Z at which $\nabla f = \vec{0}$,
since these are the points at which Z is not a surface.

Let $S = \{(x, y, z) \mid f(x, y, z) = 0 \text{ and } \nabla f(x, y, z) = \vec{0}\}$

Then $S = S_g \cup S_h$ where

$$S_g = \{(x, y, z) \mid g(x, y, z) = 0 \text{ and } \nabla f(x, y, z) = \vec{0}\}$$

$$S_h = \{(x, y, z) \mid h(x, y, z) = 0 \text{ and } \nabla f(x, y, z) = \vec{0}\}$$

Now if $\vec{x} \in S_g$ then $g(\vec{x}) = 0$ and $\vec{0} = \nabla f(\vec{x}) = g(\vec{x}) \nabla g(\vec{x}) + h(\vec{x}) \nabla g(\vec{x})$
So $h(\vec{x}) \nabla g(\vec{x}) = \vec{0}$

So $h(\vec{x}) = 0$ or $\nabla g(\vec{x}) = 0$.

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Now if $h(\vec{x})=0$ then

$$x^2 + y^2 = 1$$

$(h=0)$

and

$$x^2 + y^2 = z^2$$

$(g=0) \quad \vec{x} + \vec{z}_g$

So

$$\begin{cases} z = \pm 1 \\ x^2 + y^2 = 1 \end{cases}$$

Circles at height $z = \pm 1$
on both cylinder + cone.

$$\text{If } \vec{0} = \nabla g(\vec{x}) = (2x, 2y, -2z)$$

Then $(x, y, z) = (0, 0, 0)$ which is in S_g

$$\text{as } g(0, 0, 0) = 0.$$

So

$$S_g = \{(x, y, z) / x^2 + y^2 = 1 \text{ AND } z = \pm 1\} \cup \{(0, 0, 0)\}$$

Also $\vec{x} \in S_h \Rightarrow h(\vec{x}) = 0$ and

$$\begin{aligned} \vec{0} = \nabla f(\vec{x}) &= g(\vec{x}) \nabla h(\vec{x}) + h(\vec{x}) \nabla g(\vec{x}) \\ &= g(\vec{x}) \nabla h(\vec{x}) \end{aligned}$$

So $g(\vec{x}) = 0$ or $\nabla h(\vec{x}) = \vec{0}$.

Now $g(\vec{x}) = 0$ and $h(\vec{x}) = 0 \Rightarrow x^2 + y^2 = 1$ and $z = \pm 1$

$$\nabla h(\vec{x}) = \vec{0} = (2x, 2y, 0) \text{ only at } (x, y, z) = (0, 0, \pm 1) \text{ as above}$$

which is not in S_h .

SUMMARY: $M = \mathbb{R}^3$
 $S = \{(x, y, z) / x^2 + y^2 = 1 \text{ AND } z = \pm 1\} \cup \{(0, 0, 0)\}$

$$\text{So, } M = \mathbb{R}^3 - S, S = \{(x, y, z)\}$$