

NAME:

SOLUTIONS

1	/6	2	/17	3	/22	4	/10	5	/20	T	/75
---	----	---	-----	---	-----	---	-----	---	-----	---	-----

MATH 423 (Spring 2012) Exam 1, March 6th

No calculators, books or notes!

Show all work and give **complete explanations** for all your answers.

(1) [6 pts] Explain why the following equations are nonsensical. [Hint: Type Check!]

(a) $(f \circ \alpha)'(0) = \nabla f$, where α parametrizes a curve in \mathbb{R}^3 and $f: \mathbb{R}^3 \rightarrow \mathbb{R}$.

$f \circ \alpha: \mathbb{R} \rightarrow \mathbb{R}$ so $(f \circ \alpha)'(0)$ is a real #
 but ∇f is a vector field on \mathbb{R}^3

(b) $F_*(\mathbf{v}_p) = 3U_1(p) + 4U_2(p) + 5U_3(p)$, where $F: \mathbb{R}^3 \rightarrow \mathbb{R}^2$.

$$F_*(\mathbf{v}_p) \in T_{F(p)} \mathbb{R}^2$$

$$\text{but } 3U_1(p) + 4U_2(p) + 5U_3(p) \in T_p \mathbb{R}^3$$

(c) $v_p[fg] = v_p[f]g + v_p[g]f$, where v_p is a tangent vector to \mathbb{R}^3 at a point p and $f, g: \mathbb{R}^3 \rightarrow \mathbb{R}$.

$$\forall h: v_p[h] = \left. \frac{d}{dt} \right|_{t=0} (h(\mathbf{p} + t\mathbf{v})) \text{ is a real \#}$$

So LHS is a real #

But f, g are functions. So RHS is a function on \mathbb{R}^3

$$\vec{v}_p[fg] = v_p[f]g(p) + v_p[g]f(p)$$

(2) [17 pts]

(a) State the definition of the directional derivative, $v_p[f]$, of a function $f: \mathbb{R}^3 \rightarrow \mathbb{R}$ with respect to a tangent vector v_p to \mathbb{R}^3 at a point p .

Let $\alpha(t) = \vec{p} + t\vec{v}$ be line thru p in direction \vec{v}

$$\text{Then } \vec{v}_p[f] = (f \circ \alpha)'(0)$$

(b) Use the definition you gave in (a) to calculate $v_p[f]$ for $f(x, y, z) = x^2 + z$ with respect to the vector $v = (1, 0, 2)$ at the point $p = (1, 2, 3)$.

$$\begin{aligned}\alpha(t) &= (1, 2, 3) + t(1, 0, 2) \\ &= (1+t, 2, 3+2t)\end{aligned}$$

$$(f \circ \alpha)(t) = (1+t)^2 + 3 + 2t$$

$$(f \circ \alpha)'(t) = 2(1+t) + 2 = 4 + 2t$$

$$\vec{v}_p[f] = (f \circ \alpha)'(0) = 4$$

(c) Starting from the definition you gave in (a) prove that $v_p[f] = \nabla f(p) \cdot v$.

$$\vec{v}_p[f] = (f \circ \alpha)'(0)$$

$$= \nabla f(\alpha(0)) \cdot \alpha'(0) \quad \text{by Chain Rule}$$

for functions on curves

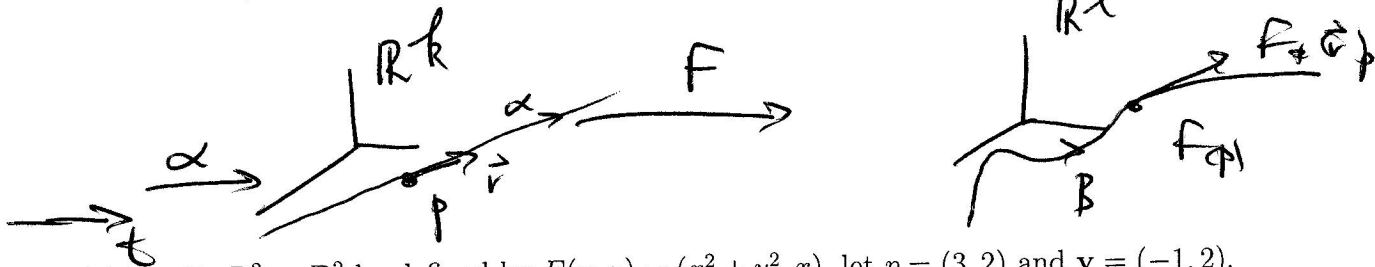
$$= \nabla f(\vec{p}) \cdot \vec{v} \quad \text{as } \alpha(t) = \vec{p} + t\vec{v} \text{ so } \alpha(0) = \vec{p}, \alpha'(0) = \vec{v}$$

(3) [22 pts]

(a) Define the tangent mapping of a mapping $F: \mathbb{R}^k \rightarrow \mathbb{R}^l$.

$F_*: T_p \mathbb{R}^k \rightarrow T_{F(p)} \mathbb{R}^l$ is defined by

$F_*(\vec{v}_p) = \beta'(0)$ where $\beta = F \circ \alpha$, $\alpha(t) = \vec{p} + t\vec{v}$



(b) Let $F: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ be defined by $F(x, y) = (x^2 + y^2, x)$, let $p = (3, 2)$ and $\mathbf{v} = (-1, 2)$.

(i) Calculate $F_*(\mathbf{v}_p)$ using the definition you gave in (a).

$$\alpha(t) = (3-t, 2+2t)$$

$$\beta(t) = F(\alpha(t)) = ((3-t)^2 + (2+2t)^2, 3-t)$$

$$\beta'(t) = (-2(3-t) + 2(2+2t) \cdot 2, -1)$$

$$\beta'(0) = (-6 + 4 \cdot 2, -1) = (2, -1)$$

$$\text{So } F_*(\vec{v}_p) = \beta'(0) = (2, -1)$$

(ii) Calculate $F_*(\vec{v}_p)$ using the matrix of partial derivatives of F .

$$Df(x,y) = \begin{pmatrix} 2x & 2y \\ 1 & 0 \end{pmatrix}$$

$$DF(p) = \begin{pmatrix} 6 & 4 \\ 1 & 0 \end{pmatrix}$$

$$F_*(\vec{v}_p) = [DF(p)] \vec{v} = \begin{pmatrix} 6 & 4 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} -1 \\ 2 \end{pmatrix} = \begin{pmatrix} 2 \\ 1 \end{pmatrix}$$

(iii) Use the Inverse Function Theorem to show that F is locally invertible at p and calculate $(F^{-1})_* \vec{w}_{F(p)}$, where $\vec{w} = (4, -3)$ and $p = (3, 2)$.

Must show $(F_*)_p : T_p \mathbb{R}^2 \rightarrow T_{F(p)} \mathbb{R}^2$ is invertible since matrix of $(F_*)_p$ is

$$DF(p) = \begin{pmatrix} 6 & 4 \\ 1 & 0 \end{pmatrix} \text{ is invertible}$$

($\det DF(p) = -4 \neq 0$) we conclude $(F_*)_p$ is invertible and so F is locally invertible at p

$$(F^{-1})_* (\vec{w}_{F(p)}) = [D(F^{-1})(F(p))] \vec{w} \stackrel{IFT}{=} [DF(p)]^{-1} \vec{w}$$

$$= \begin{pmatrix} 6 & 4 \\ 1 & 0 \end{pmatrix}^{-1} \begin{pmatrix} 4 \\ -3 \end{pmatrix} = -\frac{1}{4} \begin{pmatrix} 0 & -4 \\ -1 & 6 \end{pmatrix} \begin{pmatrix} 4 \\ -3 \end{pmatrix} = \begin{pmatrix} -3 \\ -11/2 \end{pmatrix}$$

(4) [10 pts] Let \mathbf{v} and \mathbf{w} be vectors in \mathbb{R}^3 with $\mathbf{v} \neq \mathbf{0}$ and let $\alpha : \mathbb{R} \rightarrow \mathbb{R}^3$ be the curve defined by $\alpha(t) = t^3\mathbf{v} + \mathbf{w}$.

(a) Let $t_* \in \mathbb{R}$. Calculate the length of α from $t = 0$ to $t = t_*$.

$$\begin{aligned}
 L(t_*) &= \int_0^{t_*} \|\alpha'(u)\| \, du \\
 &= \int_0^{t_*} \|3u^2 \vec{v}\| \, du \\
 &= \int_0^{t_*} 3u^2 \cdot \|\vec{v}\| \, du = \|\vec{v}\| \int_0^{t_*} 3u^2 \, du \\
 &= t_*^3 \|\vec{v}\|
 \end{aligned}$$

(b) Hence calculate a unit-speed reparameterization of α .

$$s = t^3 \|\vec{v}\| = s(t)$$

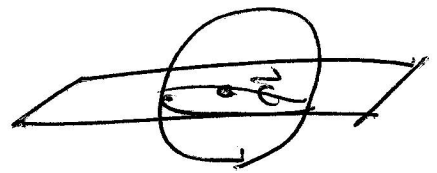
$$t = \left(\frac{s}{\|\vec{v}\|}\right)^{1/3} = t(s)$$

$$\beta(s) = \alpha(t(s)) = \alpha\left(\left(\frac{s}{\|\vec{v}\|}\right)^{1/3}\right)$$

$$= \frac{s}{\|\vec{v}\|} \vec{v} + \mathbf{w}$$

U.I.P., $\beta'(s) = \frac{\vec{v}}{\|\vec{v}\|}$ has length 1

$\{\vec{e}_1, \vec{e}_2, \vec{e}_3\}$ is ANY ONB
 not necessarily $\vec{i}, \vec{j}, \vec{k}$



(5) [20 pts] Let $r > 0$, let c be a point in \mathbb{R}^3 and let $\{e_1, e_2, e_3\}$ be an orthonormal basis for the tangent space to \mathbb{R}^3 at c . Let γ be the curve defined by

$$\gamma(s) = c + r \cos(s/r)e_1 + r \sin(s/r)e_2.$$

(a) Show that γ parametrizes the circle of radius r centered at c that lies in the plane containing the vectors e_1 and e_2 . [Hints: Use $\|a_1e_1 + a_2e_2\| = \sqrt{a_1^2 + a_2^2}$ to calculate the distance from an arbitrary point on the curve γ to c . Also explain why $\gamma(s)$ lies in the plane through c that contains the vectors e_1 and e_2 .]

$$\begin{aligned} \|\gamma(s) - c\| &= \left\| r \cos\left(\frac{s}{r}\right) \vec{e}_1 + r \sin\left(\frac{s}{r}\right) \vec{e}_2 \right\|^2 \\ &= \sqrt{r^2 \cos^2\left(\frac{s}{r}\right) + r^2 \sin^2\left(\frac{s}{r}\right)} \quad \text{by hint} \\ &= r \end{aligned}$$

So $\gamma(s)$ lies on SPHERE center c radius r

Also $\gamma(s) = c + a\vec{e}_1 + b\vec{e}_2$ where $a = r \cos\left(\frac{s}{r}\right)$
 $b = r \sin\left(\frac{s}{r}\right)$

So $\gamma(s)$ is in plane thru c containing \vec{e}_1, \vec{e}_2 .

The intersection of this plane + sphere is the circle radius r center c

(b) Show that γ is a unit speed curve.

$$\gamma'(s) = -\sin\left(\frac{s}{r}\right) \vec{e}_1 + \cos\left(\frac{s}{r}\right) \vec{e}_2$$

So by hint above

$$\|\gamma'(s)\| = \sqrt{\sin^2\left(\frac{s}{r}\right) + \cos^2\left(\frac{s}{r}\right)} = 1$$

(c) Calculate the Frenet frame, T , N , and B , of the curve γ . Hence find the curvature and torsion of γ .
 [Hint: Express T , N , and B in terms of s , r , e_1 and e_2 .]

$$T = \gamma' = -\sin\left(\frac{s}{r}\right) \vec{e}_1 + \cos\left(\frac{s}{r}\right) \vec{e}_2$$

$$T' = \gamma'' = -\frac{1}{r} \cos\left(\frac{s}{r}\right) \vec{e}_1 - \frac{1}{r} \sin\left(\frac{s}{r}\right) \vec{e}_2$$

$$K = \|T'\| = \frac{1}{r} \text{ by hint to (a)}$$

$$N = \frac{T'}{K} = -\cos\left(\frac{s}{r}\right) \vec{e}_1 - \sin\left(\frac{s}{r}\right) \vec{e}_2$$

$$B = T \times N$$

$$= \left(-\sin\left(\frac{s}{r}\right) \vec{e}_1 + \cos\left(\frac{s}{r}\right) \vec{e}_2 \right) \times \left(-\cos\left(\frac{s}{r}\right) \vec{e}_1 - \sin\left(\frac{s}{r}\right) \vec{e}_2 \right)$$

$$= \sin^2\left(\frac{s}{r}\right) \vec{e}_1 \times \vec{e}_2 - \cos^2\left(\frac{s}{r}\right) \vec{e}_2 \times \vec{e}_1$$

$$= \vec{e}_1 \times \vec{e}_2 \quad (\text{CONSTANT})$$

$$B' = 0 \quad \text{So} \quad B' = -\tau N, \quad N \neq \vec{0} \Rightarrow \tau = 0$$

Pledge: I have neither given nor received aid on this exam

Signature: _____