

NAME: SOLUTIONS

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MATH 423 (Spring 2012) Exam II, April 12th

No calculators, books or notes!

Show all work and give **complete explanations** for all your answers.

(1) [12 pts]

(a) Define the concept of a 1-form on  $\mathbb{R}^3$ .

A 1-form  $\omega$  on  $\mathbb{R}^3$  is a choice of linear transformations

$$\omega_p : T_p \mathbb{R}^3 \rightarrow \mathbb{R} \text{ for each } p \in \mathbb{R}^3.$$

ie If  $\vec{v} \in T_p \mathbb{R}^3$  then  $\omega_p(\vec{v}) \in \mathbb{R}$  and

$$\omega_p(c_1 \vec{v}_1 + c_2 \vec{v}_2) = c_1 \omega_p(\vec{v}_1) + c_2 \omega_p(\vec{v}_2) \quad \forall c_j \in \mathbb{R}, \vec{v}_j \in T_p \mathbb{R}^3$$

(b) Let  $V$  be a vector field on  $\mathbb{R}^3$ . Define  $\omega$  by  $\omega_p(\vec{w}) = \vec{w} \cdot V(p)$ , where  $p$  is a point in  $\mathbb{R}^3$  and  $\vec{w}$  is a tangent vector to  $\mathbb{R}^3$  at  $p$ . Prove that  $\omega$  is a 1-form on  $\mathbb{R}^3$ .

$$\omega_p(\vec{w}) \in \mathbb{R}, \text{ so } \omega_p : T_p \mathbb{R}^3 \rightarrow \mathbb{R}.$$

Check linearity

$$\omega_p(c_1 \vec{w}_1 + c_2 \vec{w}_2) = (c_1 \vec{w}_1 + c_2 \vec{w}_2) \cdot V(p)$$

$$= c_1 \vec{w}_1 \cdot V(p) + c_2 \vec{w}_2 \cdot V(p)$$

$$= c_1 \omega_p(\vec{w}_1) + c_2 \omega_p(\vec{w}_2) \quad \checkmark$$

(2) [16 pts]

(a) Define the concept of a *coordinate patch*.

A coordinate patch is a 1-1, regular, mapping  $\vec{r}: D \rightarrow \mathbb{R}^3$  where  $D$  is an open subset of  $\mathbb{R}^2$ .

$\vec{r}$  regular means  $\vec{r}_* : T_p \mathbb{R}^2 \rightarrow T_{\vec{r}(p)} \mathbb{R}^3$   
 $\approx$  1-1  $\forall p \in D$ .

(b) Does the equation  $(x^2 + y^2)^2 + 4z^2 - 16z + 15 = 0$  define a surface?

$$F(x, y, z) = (x^2 + y^2)^2 + 4z^2 - 16z + 15$$

$$\nabla F = (4x(x^2 + y^2), 4y(x^2 + y^2), 8z - 16) = (0, 0, 0)$$

at  $(x, y, z) = (0, 0, 2)$ .

$$\text{Since } F(0, 0, 2) = 4 \cdot 4 - 16 \cdot 2 + 15 = -1 \neq 0$$

we conclude  $\nabla F \neq \vec{0}$  on  $F=0$

So by Implicit Function Thm  $\{F=0\}$  is a surface.

Also Need to ensure  $\{F=0\}$  is non empty. Regard  $F$  as quadratic in  $z$ . Do the  $z$  sol<sup>n</sup>?

$$\Delta = b^2 - 4ac = (-16)^2 - 4 \cdot 4 \cdot (15 + (x^2 + y^2)^2) = 16(16 - 15 - (x^2 + y^2)^2) > 0$$

(3) [12 pts] Let  $M$  be the surface parametrized by  $\mathbf{x}(u, v) = (u \cos v, u \sin v, v)$  for  $0 < u < 1$  and  $0 < v < \pi$ . Orient  $M$  using the upward normal. Let  $\mathbf{F}$  be the vector field on  $\mathbf{R}^3$  defined by  $\mathbf{F}(x, y, z) = (y, x, z^2)$ . Calculate  $\iint_M \mathbf{F} \cdot d\mathbf{A}$ .

$$\iint_M \mathbf{F} \cdot d\mathbf{A} = \int_{u=0}^1 \int_{v=0}^{\pi} \mathbf{F}(u \cos v, u \sin v, v) \cdot \left( \frac{\partial \mathbf{x}}{\partial u} \times \frac{\partial \mathbf{x}}{\partial v} \right) dv du$$

Now

$$\frac{\partial \mathbf{x}}{\partial u} \times \frac{\partial \mathbf{x}}{\partial v} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ \cos v & \sin v & 0 \\ -u \sin v & u \cos v & 1 \end{vmatrix}$$

$$= (\sin v, -\cos v, u)$$

Since 3rd cpt so  $u > 0$  we know

$\frac{\partial \mathbf{x}}{\partial u} \times \frac{\partial \mathbf{x}}{\partial v}$  points upwards  $\checkmark$ .

So

$$\iint_M \mathbf{F} \cdot d\mathbf{A} = \int_{u=0}^1 \int_{v=0}^{\pi} (u \sin v, -u \cos v, v^2) \cdot (\sin v, -\cos v, u) dv du$$

$$= \int_{u=0}^1 \int_{v=0}^{\pi} u (\sin^2 v + \cos^2 v) + v^2 u dv du$$

$$= \int_{u=0}^1 \int_{v=0}^{\pi} + u \cancel{\cos 2v} + v^2 u dv du = \int_0^1 u du \int_0^{\pi} (1 + v^2) dv$$

$$= \frac{1}{2} \left[ v + \frac{v^3}{3} \right]_0^{\pi} = \frac{\pi + \pi^3/3}{2}$$

(4) [15 pts] The *catenoid*,  $M$ , is the surface obtained by rotating the catenary curve  $z = \cosh y$  about the  $y$ -axis. [Recall that  $\cosh x = (e^x + e^{-x})/2$  and  $\sinh x = (e^x - e^{-x})/2$ .]

(a) Find a formula for a coordinate patch  $\mathbf{x} : D \rightarrow \mathbf{R}^3$  for  $M$ . Make sure you specify the domain  $D$  of  $\mathbf{x}$ . [Do *not* prove that  $\mathbf{x}$  is a patch, just write down a formula for it.]

$$x = \cosh u \cos v$$

$$y = u$$

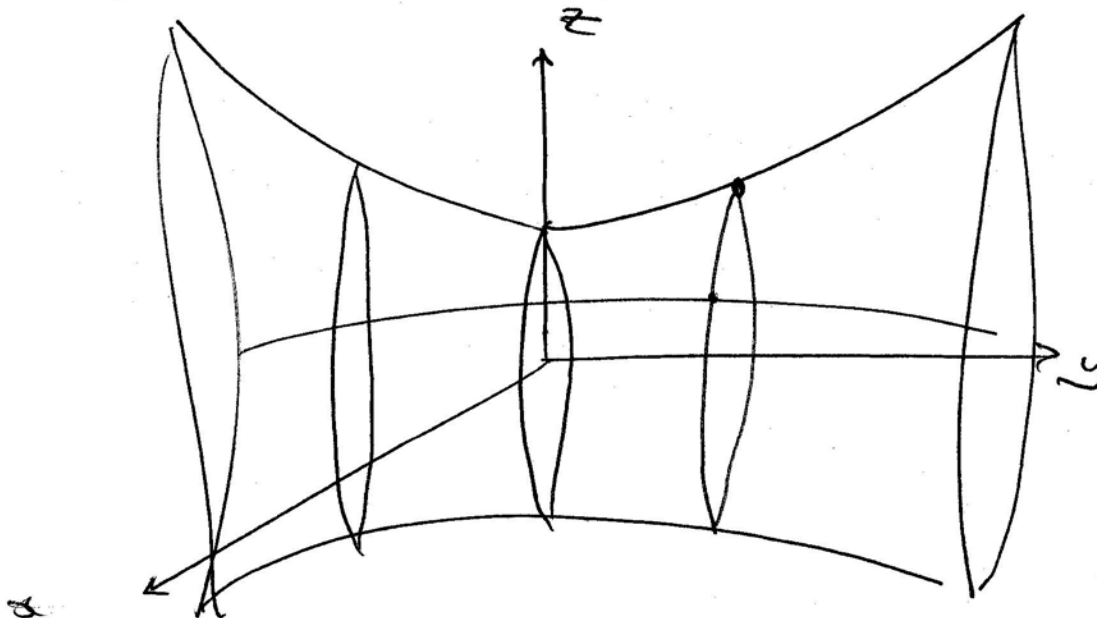
$$z = \cosh u \sin v$$

$$u \in \mathbb{R}$$

$$v \in (0, 2\pi)$$

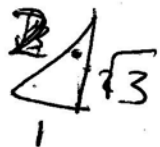
$$\alpha(u) = (u, \cosh u)$$

(b) Sketch  $M$  together with some of its coordinate (grid) curves.



(c) Calculate a parametrization of the tangent plane to  $M$  at the point  $(x, y, z) = (\frac{\sqrt{3}}{2} \cosh 1, 1, \frac{1}{2} \cosh 1)$ .

$$u = 1, \quad v = \pi/6$$



$$\begin{aligned} \vec{x}_u &= (\sinh u \cos v, 1, \sinh u \sin v) \\ &= (\sinh 1 \frac{\sqrt{3}}{2}, 1, (\sinh 1) \frac{1}{2}) \end{aligned}$$

$$\vec{x}_v = (-\cosh u \sin v, 0, \cos v \cosh u) = (-\frac{1}{2} \cosh 1, 0, \frac{\sqrt{3}}{2} \cosh 1)$$

$$\begin{aligned} L(s, t) &= (\frac{\sqrt{3}}{2} \cosh 1, 1, \frac{1}{2} \cosh 1) + s (\frac{\sqrt{3}}{2} \sinh 1, 1, \frac{1}{2} \sinh 1) \\ &\quad + t (-\frac{1}{2} \cosh 1, 0, \frac{\sqrt{3}}{2} \cosh 1) \end{aligned}$$

(5) [8 pts] Let  $\mathbf{F}$  be the vector field on  $\mathbb{R}^3$  given by  $\mathbf{F} = xy\mathbf{i} + yz\mathbf{j} + xz\mathbf{k}$ . About what axis is the circulation of  $\mathbf{F}$  the greatest at the point  $(2, 1, 3)$ ?

$$\begin{aligned} \nabla \times \mathbf{F} &= \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ xy & yz & xz \end{vmatrix} = (-y, -z, -x) \\ &= (-1, -3, -2) \text{ at } (2, 1, 3) \end{aligned}$$

Circle

Circulation is greatest about axis give by  $\nabla \times \mathbf{F}$  at the point. So axis is  $(-1, -3, -2)$

(6) [12 pts] (a) Give a careful statement of the Divergence Theorem.

Let  $V$  be a solid region in  $\mathbb{R}^3$ . Let  $\vec{F}$  be a VF on  $V$ .  
 Let  $S = \partial V$  be boundary surface of  $V$  oriented outwards. Then

$$\iiint_V (\nabla \cdot \vec{F}) dV = \iint_{\partial V} \vec{F} \cdot d\vec{A}.$$

(b) Let  $\mathbf{F}$  be a vector field on  $\mathbb{R}^3$ . Let  $p \in \mathbb{R}^3$  and let  $B_\epsilon$  be the ball of radius  $\epsilon > 0$  centered at  $p$ . (So  $B_\epsilon$  is a three-dimensional solid.) Let  $\partial B_\epsilon$  denote the boundary surface of  $B_\epsilon$ , oriented using the outward pointing normal vector field. Prove that

$$(\nabla \cdot \mathbf{F})(p) = \lim_{\epsilon \rightarrow 0} \frac{1}{\text{Vol}(B_\epsilon)} \iint_{\partial B_\epsilon} \mathbf{F} \cdot d\mathbf{A}.$$

$$(\nabla \cdot \vec{F})(p) = \lim_{\epsilon \rightarrow 0} \frac{\iiint_{B_\epsilon} (\nabla \cdot \vec{F}) dV}{\text{Vol}(B_\epsilon)}$$

by MVT  
Integrals

$$= \lim_{\epsilon \rightarrow 0} \frac{\iint_{\partial B_\epsilon} \vec{F} \cdot d\vec{A}}{\text{Vol}(B_\epsilon)}$$

(c) IF  $\vec{F} = \rho \vec{v}$  THEN units of RHS are  $\frac{1}{m^3} \cdot \frac{kg}{m^3} \cdot \frac{m}{s} \cdot m^2 = \frac{kg}{m^3 s}$   
 So  $\nabla \cdot \vec{F}(p) =$  Rate of ~~change~~ decrease of fluid density at  $p$

Pledge: I have neither given nor received aid on this exam

Signature: \_\_\_\_\_

as  $\nabla \cdot \mathbf{F}(p) > 0$  means fluid