

## ROBERT D. GREGG IV

Eugene McDermott Professor

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### POSITIONS

<b><i>Fellow, Eugene McDermott Professor, University of Texas at Dallas</i></b>	2018 – Present
<b><i>Assistant Professor, University of Texas at Dallas</i></b> Department of Bioengineering and Department of Mechanical Engineering	2013 – Present
<b><i>Adjunct Assistant Professor, UT Southwestern Medical Center</i></b> Prosthetics-Orthotics Program	2014 – Present
<b><i>Research Scientist, Rehabilitation Institute of Chicago</i></b> Center for Bionic Medicine	2012 – 2013

### EDUCATION

<b><i>Postdoctoral Fellow, Rehabilitation Institute of Chicago</i></b> Center for Bionic Medicine	2010 – 2012
<b><i>Postdoctoral Fellow, Northwestern University</i></b> Department of Mechanical Engineering	2010 – 2012
<b><i>PhD, University of Illinois at Urbana-Champaign</i></b> Department of Electrical and Computer Engineering <i>Dissertation:</i> "Geometric Control and Motion Planning for 3D Bipedal Locomotion" <i>Advisor:</i> Mark W. Spong, PhD	Aug 2010
<b><i>MS, University of Illinois at Urbana-Champaign</i></b> Department of Electrical and Computer Engineering	Dec 2007
<b><i>BS (cum laude), University of California – Berkeley</i></b> Department of Electrical Engineering and Computer Sciences	May 2006

### RESEARCH INTERESTS

Wearable Robots, Legged Robots, Prosthetics & Orthotics, Bipedal Locomotion, Nonlinear Control Theory, Rehabilitation Engineering

### HONORS AND AWARDS

#### Personal:

- Provost's Award for Faculty Excellence in Undergrad Research Mentoring, UT Dallas, 2018.
- Eugene McDermott Professorship, University of Texas at Dallas, 2018.

- ICRA Conference Editorial Board Best Associate Editor Award, 2018.
- Bioengineering Undergraduate Teaching Award, University of Texas at Dallas, 2017-18.
- Bioengineering Graduate Student Mentoring Award, University of Texas at Dallas, 2017-18.
- Best Student Robotics Paper Award (advisor), *ASME Dyn Sys Control Conf*, 2017.
- Technology Inventors Award Finalist, Tech Titans, Technology Assoc for North Texas, 2017.
- NSF CAREER Award, Directorate for Engineering, National Science Foundation, 2017.
- Best Student Paper Award Finalist (advisor), *IEEE Conf Control Tech & App*, Hawaii, 2017.
- Jonsson School Junior Faculty Research Award, University of Texas at Dallas, 2016.
- IEEE Senior Member, Institute of Electrical & Electronics Engineers, 2016.
- Best Student Paper Award (advisor), *IEEE Conf Decision & Control*, Osaka, Japan, 2015.
- Excellence in Biomedical Research Award, Department of Bioengineering, UT Dallas, 2014.
- NIH Director's New Innovator Award, National Institutes of Health, 2013.
- Career Award at the Scientific Interface, Burroughs Wellcome Fund, 2012.
- Best Technical Paper Award (co-author), *CLAWAR Conference*, 2011.
- Engineering into Medicine Postdoctoral Fellowship, Northwestern University, 2010.
- O. Hugo Schuck Award (Best Paper), IFAC American Automatic Control Council, 2009.
- Best Student Paper Award, *American Control Conference*, Seattle, WA, 2008.
- Warren Dere Design Award, Department of EECS, UC Berkeley, 2007.
- First Place, NATCAR Intercollegiate Design Contest, UC Davis, 2006.
- Arthur M. Hopkin Award, Department of EECS, UC Berkeley, 2006.
- Christie Senior Research Award, California Alumni Association, UC Berkeley, 2006.

#### **Trainees:**

- Siavash Rezazadeh, BME Department Staff Research Impact Award, 2018.
- Chris Nesler, BME Department Staff Undergraduate Research Mentoring Award, 2018.
- Nikhil Divekar, Jonsson Family Graduate Fellowship in Bioengineering, Jonsson School of Engineering and Computer Science, UT Dallas, 2018.
- Edgar Bolivar, Best Student Robotics Paper Award, *ASME Dyn Sys Control Conf*, 2017.
- Ge Lv, Louis Beecherl Jr. Graduate Fellowship, Jonsson School of Engineering and Computer Science, UT Dallas, 2017-18.
- Saurav Kumar, Best Student Paper Award Finalist, *IEEE Conf Control Tech & App*, 2017.
- Rafi Ayub, NSF Graduate Research Fellowship, National Science Foundation, 2017.
- Ge Lv, Best Student Paper Award, *IEEE Conf Decision & Control*, Osaka, Japan, 2015.
- Dario Villarreal, Jonsson Family Graduate Fellowship in Bioengineering, Jonsson School of Engineering and Computer Science, UT Dallas, 2015.
- David Allen, Excellence in Education Doctoral Fellowship, Jonsson School of Engineering and Computer Science, UT Dallas, 2015.
- Hanqi "Leon" Zhu, Founder's Distinguished Graduate Fellowship, UT Dallas, 2015.
- Kyle Embry, Excellence in Education Doctoral Fellowship, Jonsson School of Engineering and Computer Science, UT Dallas, 2014-15.
- David Quintero, Excellence in Education Doctoral Fellowship, Jonsson School of Engineering and Computer Science, UT Dallas, 2013-15.
- Dario Villarreal, Conacyt Graduate Fellowship, CONACYT, Mexico, 2013.

## **RESEARCH FUNDING**

#### **Active:**

1. **R. Gregg** (UTD/Lead PI), S. Rezazadeh (UTD Co-PI), and E. Rouse (Michigan PI), “*NRI: FND: COLLAB: Optimal Design of Robust Compliant Actuators for Ubiquitous Co-Robots*,” National Robotics Initiative 2.0, National Science Foundation (CMMI-1830360), 09/15/18–08/31/21, \$750,000 (\$431,244 UTD share).
2. **R. Gregg** (PI), “*Controlling Locomotion over Continuously Varying Activities for Agile Powered Prosthetic Legs*,” National Institutes of Health/NICHHD (R01HD094772), 09/01/18–05/31/2023, \$2,227,090. Percentile: 9%.
3. **R. Gregg** (UTD PI), H. Geyer (CMU PI), and E. Rouse (Michigan/Lead PI), “*NRI: FND: COLLAB: An Open-Source Robotic Leg Platform that Lowers the Barrier for Academic Research*,” National Robotics Initiative 2.0, National Science Foundation (CMMI-1734600), 10/01/17–09/30/20, \$749,054 (\$193,000 UTD share).
4. **R. Gregg** (PI), “*CAREER: Recovering and Enhancing Natural Locomotion in Changing Conditions with Powered Lower-Limb Prostheses and Orthoses*,” National Science Foundation (CMMI-1652514), 09/01/17–08/31/22, \$500,000.
5. N. Gans (PI) and **R. Gregg** (Co-PI), “*Time-Invariant, Multi-Objective Extremum Seeking Control for Model-Free Auto-Tuning of Powered Prosthetic Legs*,” National Science Foundation (CMMI-1728057), 09/01/17–08/31/20, \$373,483.
6. K. Hamed (SDSU PI) and **R. Gregg** (UTD PI), “*NRI: Decentralized Feedback Control Design for Cooperative Robotic Walking with Application to Powered Prosthetic Legs*,” National Robotics Initiative, National Science Foundation (CMMI-1637704), 09/01/16–08/31/19, \$612,213 (\$245,730 UTD share).
7. **R. Gregg** (PI), “*From Machine to Biomimetic Control in Robot-Assisted Walking*,” Career Award at the Scientific Interface, Burroughs Wellcome Fund, 07/01/12–06/30/20, \$500,000.

#### Completed:

1. **R. Gregg** (PI), “*Phase-Based Control of Locomotion for High-Performance Prostheses and Orthoses*,” NIH Director’s New Innovator Award, National Institutes of Health/NICHHD (DP2HD080349), 09/30/13–06/30/18, \$2,295,000. Impact Score: 18.

#### PEER-REVIEWED JOURNAL ARTICLES

1. K. Hamed, B. Safaee, and **R. Gregg**, “Dynamic Output Controllers for Exponential Stabilization of Periodic Orbits for Multi-Domain Hybrid Models of Robotic Locomotion,” *ASME Journal of Dynamic Systems, Measurement, and Control*, under review.
2. T. Elery, S. Rezazadeh, C. Nesler, and **R. Gregg**, “Design and Validation of a Powered Knee-Ankle Prosthesis with High-Torque, Low-Impedance Actuators,” *IEEE Transactions on Robotics*, under review.
3. A. Mohammadi and **R. Gregg**, “Variable Impedance Control of Powered Knee Prostheses Using Human-Inspired Algebraic Curves,” *ASME Journal of Nonlinear and Computational Dynamics* (Special Issue on Nonlinear and Computational Dynamics in Biomedical Applications), under review.
4. M. Yeatman, G. Lv, and **R. Gregg**, “Decentralized Passivity-Based Control with a Generalized Energy Storage Function for Robust Biped Locomotion,” *ASME Journal of Dynamic Systems, Measurement, and Control*, under review.
5. S. Kumar, A. Mohammadi, D. Quintero, S. Rezazadeh, N. Gans, and **R. Gregg**, “Extremum Seeking Control for Model-Free Auto-Tuning of Powered Prosthetic Legs,” *IEEE Trans Control Systems Technology*, under review.

6. S. Rezazadeh, D. Quintero, N. Divekar, E. Reznick, L. Gray, and **R. Gregg**, "A Phase Variable Approach for Improved Volitional and Rhythmic Control of a Powered Knee-Ankle Prosthesis," *IEEE Transactions on Robotics*, under review.
7. E. Bolivar, S. Rezazadeh, T. Summers, and **R. Gregg**, "Robust Optimal Design of Series Elastic Actuators: Application to a Powered Prosthetic Ankle," *IEEE Robotics & Automation Letters*, under review.
8. H. Zhu, J. Doan, C. Stence, G. Lv, T. Elery, and **R. Gregg**, "A Powered Knee-Ankle Orthosis with Quasi-Direct Drive Actuation for Partial Gait Assistance," *IEEE/ASME Transactions on Mechatronics*, under review.
9. D. Allen, E. Bolivar, S. Farmer, W. Voit, and **R. Gregg**, "Mechanical Simplification of Variable Stiffness Actuators Using Dielectric Elastomer Systems," *IEEE Transactions on Robotics*, under review.
10. E. Bolivar, S. Rezazadeh, and **R. Gregg**, "Minimizing Energy Consumption and Peak Power of Series Elastic Actuators: A Convex Optimization Framework for Elastic Element Design," *IEEE/ASME Transactions on Mechatronics*, under review.
11. J. Horn, A. Mohammadi, K. Hamed, and **R. Gregg**, "Hybrid Zero Dynamics of Bipedal Robots Under Nonholonomic Virtual Constraints," *IEEE Control Systems Letters*, 2018, in press.
12. K. Embry, D. Villarreal, R. Macaluso, and **R. Gregg**, "Modeling the Kinematics of Human Locomotion over Continuously Varying Speeds and Inclines," *IEEE Trans Neural Sys Rehab Eng*, 26(12): 2342-2350, 2018.
13. D. Quintero, E. Reznick, D. Lambert, S. Rezazadeh, L. Gray, and **R. Gregg**, "Intuitive Clinician Control Interface for a Powered Knee-Ankle Prosthesis: A Case Study," *IEEE Journal of Translational Engineering in Health and Medicine*, 6(1): 1-9, 2018.
14. G. Lv, H. Zhu, and **R. Gregg**, "On the Design and Control of Highly Backdrivable Lower-limb Exoskeletons," *IEEE Control Systems Magazine*, 38(6): 88-113, 2018.
15. K. Hamed and **R. Gregg**, "Decentralized Event-Based Controllers for Robust Stabilization of Hybrid Periodic Orbits: Application to Underactuated 3D Bipedal Walking," *IEEE Trans Automatic Control*, 2018, doi: 10.1109/TAC.2018.2863184.
16. D. Quintero, D. Villarreal, D. Lambert, S. Kapp, and **R. Gregg**, "Continuous-Phase Control of a Powered Knee-Ankle Prosthesis: Amputee Experiments Across Speeds and Inclines," *IEEE Trans Robotics*, 34(3): 686-701, 2018.
17. G. Lv and **R. Gregg**, "Underactuated Potential Energy Shaping with Contact Constraints: Application to a Powered Knee-Ankle Orthosis," *IEEE Trans Contr Sys Tech*, 26(1): 181-193, 2018.
18. D. Quintero, A. Martin, and **R. Gregg**, "Toward Unified Control of a Powered Prosthetic Leg: A Simulation Study," *IEEE Trans Control Systems Technology*, 26(1): 305-312, 2018.
19. A. Martin and **R. Gregg**, "Stable, Robust Hybrid Zero Dynamics Control of Powered Lower-Limb Prostheses," *IEEE Trans Automatic Control*, 62(8): 3930-3942, 2017.
20. K. Hamed and **R. Gregg**, "Decentralized Feedback Controllers for Robust Stabilization of Periodic Orbits of Hybrid Systems: Application to Bipedal Walking," *IEEE Trans Control Systems Technology*, 25(4): 1153-1167, 2017.
21. D. Villarreal, H. Poonawala, and **R. Gregg**, "A Robust Parameterization of Human Gait Patterns Across Phase-Shifting Perturbations," *IEEE Trans Neural Sys Rehab Eng*, 25(3): 265-278, 2017.
22. R. Ayub, D. Villarreal, **R. Gregg**, and F. Gao, "Evaluation of Transradial Body-Powered Prostheses Using a Robotic Simulator," *Prosthetics Orthotics Int*, 41(2): 194-200, 2017.

23. A. Plauché, D. Villarreal, and **R. Gregg**, “A Haptic Feedback System for Phase-Based Sensory Restoration in Above-Knee Prosthetic Leg Users,” *IEEE Trans Haptics*, 9(3): 421-426, 2016.
24. D. Villarreal, D. Quintero, and **R. Gregg**, “A Perturbation Mechanism for Investigations of Phase-Dependent Behavior in Human Locomotion,” *IEEE Access*, 4: 893-904, 2016.
25. A. Martin and **R. Gregg**, “Incorporating Human-like Walking Variability in an HZD-Based Bipedal Model,” *IEEE Trans Robotics* (Special Issue on Movement Science for Humans and Humanoids: Methods and Applications), 32(4): 943-948, 2016.
26. A. Martin, D. Villarreal, and **R. Gregg**, “Characterizing and Modeling the Joint-level Variability in Human Walking,” *J Biomechanics*, 49(14): 3298-3305, 2016.
27. **R. Gregg**, T. Lenzi, L. Hargrove, and J. Sensinger, “Virtual Constraint Control of a Powered Prosthetic Leg: From Simulation to Experiments with Transfemoral Amputees,” *IEEE Trans Robotics*, 30(6): 1455-1471, 2014.
28. **R. Gregg**, E. Rouse, L. Hargrove, and J. Sensinger, “Evidence for a Time-Invariant Phase Variable in Human Ankle Control,” *PLoS ONE*, 9(2): e89163, 2014.
29. **R. Gregg** and J. Sensinger, “Towards Biomimetic Virtual Constraint Control of a Powered Prosthetic Leg,” *IEEE Trans Control Systems Technology*, 22(1): 246-254, 2014.
30. A. Degani, A. Long, S. Feng, B. Brown, **R. Gregg**, H. Choset, M. Mason, and K. Lynch, “Design and Open-Loop Control of the ParkourBot, a Dynamic Climbing Robot,” *IEEE Trans Robotics*, 30(3): 705-718, 2014.
31. **R. Gregg** and L. Righetti, “Controlled Reduction with Unactuated Cyclic Variables: Application to 3D Bipedal Walking with Passive Yaw Rotation,” *IEEE Trans Automatic Control*, 58(10): 2679-2685, 2013.
32. E. Rouse, **R. Gregg**, L. Hargrove, and J. Sensinger, “The Difference Between Mechanical Stiffness and Quasi-Stiffness in the Context of Biomechanical Modeling,” *IEEE Trans Biomed Eng*, 60(2): 562-568, 2013.
33. **R. Gregg**, Y. Dhaher, A. Degani, and K. Lynch, “On the Mechanics of Functional Asymmetry in Bipedal Walking,” *IEEE Trans Biomed Eng*, 59(5): 1310-1318, 2012.
34. **R. Gregg**, A. Tilton, S. Candido, T. Bretl, and M. Spong, “Control and Planning of 3D Dynamic Walking with Asymptotically Stable Gait Primitives,” *IEEE Trans Robotics*, 28(6): 1415-1423, 2012.
35. **R. Gregg** and M. Spong, “Reduction-Based Control of Three-Dimensional Bipedal Walking Robots,” *Int J Robotics Research*, 29(6): 680-702, 2010.

## PEER-REVIEWED CONFERENCE PROCEEDINGS

1. J. Lin, G. Lv, and **R. Gregg**, “Contact-Invariant Total Energy Shaping for Powered Exoskeletons,” submitted to *American Control Conference*, 2019.
2. S. Kumar, A. Mohammadi, **R. Gregg**, and N. Gans, “Limit Cycle Minimization by Time-Invariant Extremum Seeking Control,” submitted to *American Control Conference*, 2019.
3. A. Mohammadi, S. Fakoorian, J. Horn, D. Simon, and **R. Gregg**, “Hybrid Nonlinear Disturbance Observer Design for Underactuated Bipedal Robots,” to appear in *IEEE Conf. Decision & Control*, 2018.
4. S. Rezazadeh, D. Quintero, N. Divekar, and **R. Gregg**, “A Phase Variable Approach to Volitional Control of Powered Knee-Ankle Prostheses,” in *IEEE Int Conf Intelligent Robots & Systems*, Spain, 2018. (46.7% acceptance rate)

5. A. Mohammadi and **R. Gregg**, "Human-Inspired Algebraic Curves for Wearable Robot Control," in *ASME Dynamic Systems & Control Conference*, 2018.
6. T. Elery, S. Rezazadeh, C. Nesler, J. Doan, H. Zhu, and **R. Gregg**, "Design and Benchtop Validation of a Powered Knee-Ankle Prosthesis with High-Torque, Low-Impedance Actuators," in *IEEE Int Conf Robotics & Automation*, Brisbane, Australia, 2018. (41% acceptance rate)
7. M. Yeatman, G. Lv, and **R. Gregg**, "Passivity-Based Control with a Generalized Energy Storage Function for Robust Bipedal Walking," in *American Control Conference*, Milwaukee, WI, 2018.
8. K. Hamed, **R. Gregg**, and A. Ames, "Exponentially Stabilizing Controllers for Multi-Contact 3D Bipedal Locomotion," in *American Control Conference*, Milwaukee, WI, 2018.
9. K. Hamed, A. Ames, and **R. Gregg**, "Observer-Based Feedback Controllers for Exponential Stabilization of Hybrid Periodic Orbits: Application to Underactuated Bipedal Walking," in *American Control Conference*, Milwaukee, WI, 2018.
10. D. Allen, S. Farmer, **R. Gregg**, and W. Voit, "Stretchable conductive fabric simplifies manufacturing of low-resistance dielectric-elastomer-system electrodes," *SPIE Electroactive Polymer Actuators and Devices*, 2018.
11. E. Bolivar, S. Rezazadeh, and **R. Gregg**, "A General Framework for Minimizing Energy Consumption of Series Elastic Actuators with Regeneration," in *ASME Dynamic Systems & Control Conf*, Virginia, pp. V001T36A005, 2017. **Best Student Robotics Paper Award**.
12. A. Mohammadi, J. Horn, and **R. Gregg**, "Removing Phase Variables from Biped Robot Parametric Gaits," in *IEEE Conf on Control Tech & Applications* (Invited Session on Robotic Locomotion Control), Hawaii, pp. 834-840, 2017.
13. S. Kumar, A. Mohammadi, N. Gans, and **R. Gregg**, "Automatic Tuning of Virtual Constraint-Based Control Algorithms for Powered Knee-Ankle Prostheses," in *IEEE Conf on Control Tech & Applications* (Invited Session on Robotic Locomotion Control), Hawaii, pp. 812-818, 2017. **Best Student Paper Award Finalist**.
14. D. Quintero, D. Lambert, D. Villarreal, and **R. Gregg**, "Real-Time Continuous Gait Phase and Speed Estimation from a Single Sensor," in *IEEE Conf on Control Tech & Applications* (Invited Session on Robotic Locomotion Control), Hawaii, pp. 847-852, 2017.
15. D. Villarreal, D. Quintero, and **R. Gregg**, "Piecewise and Unified Phase Variables in the Control of a Powered Prosthetic Leg," in *IEEE Int Conf Rehab Robotics*, London, pp. 1425-1430, 2017.
16. G. Lv and **R. Gregg**, "Towards Total Energy Shaping Control of Lower-Limb Exoskeletons," in *American Control Conference*, Seattle, WA, pp. 4851-4857, 2017.
17. H. Zhu, J. Doan, C. Stence, G. Lv, T. Elery, and **R. Gregg**, "Design and Validation of a Torque Dense, Highly Backdrivable Powered Knee-Ankle Orthosis," in *IEEE Int Conf Robotics & Automation*, Singapore, pp. 504-510, 2017. (41% acceptance rate)
18. S. Rezazadeh and **R. Gregg**, "A Control Framework for Anthropomorphic Biped Walking Based on Stabilizing Feedforward Trajectories," in *ASME Dynamic Systems & Control Conference*, Minneapolis, MN, pp. V001T06A007, 2016.
19. E. Bolivar, D. Allen, G. Ellson, J. Cossio, W. Voit, and **R. Gregg**, "Towards a Series Elastic Actuator with Electrically Modulated Stiffness for Powered Ankle-Foot Orthoses," in *IEEE Conf Automation Science & Engineering*, Fort Worth, TX, pp. 1086-1093, 2016.
20. D. Quintero, D. Villarreal, and **R. Gregg**, "Preliminary Experiments with a Unified Controller for a Powered Knee-Ankle Prosthetic Leg Across Walking Speeds," in *IEEE Int Conf Intelligent Robots & Systems*, Daejeon, Korea, pp. 5427-5433, 2016. (48% acceptance rate)

21. K. Embry, D. Villarreal, and **R. Gregg**, "A Unified Parameterization of Human Gait Across Ambulation Modes," in *IEEE Eng Medicine Biology Conf*, Orlando, FL, pp. 2179-2183, 2016.
22. D. Villarreal and **R. Gregg**, "Unified Phase Variables of Relative Degree Two for Human Locomotion," in *IEEE Eng Medicine Biology Conf*, Orlando, FL, pp. 6262-6267, 2016.
23. **R. Gregg** and A. Martin, "Prosthetic Leg Control in the Nullspace of Human Interaction," in *American Control Conf* (Invited Session on Control Theory in Legged Locomotion), Boston, MA, pp. 4814-4821, 2016.
24. K. Hamed and **R. Gregg**, "Decentralized Feedback Controllers for Exponential Stabilization of Hybrid Periodic Orbits: Application to Robotic Walking," in *American Control Conf* (Invited Session on Control Theory in Legged Locomotion), Boston, MA, pp. 4793-4800, 2016.
25. G. Lv, H. Zhu, T. Elery, L. Li, and **R. Gregg**, "Experimental Implementation of Underactuated Potential Energy Shaping on a Powered Ankle-Foot Orthosis," in *IEEE Int Conf Robotics & Automation*, Stockholm, Sweden, pp. 3493-3500, 2016. (34.7% acceptance rate)
26. D. Villarreal, D. Quintero, and **R. Gregg**, "A Perturbation Mechanism for Investigations of Phase Variables in Human Locomotion," in *IEEE Int Conf Robotics & Biomimetics*, Zhuhai, China, pp. 2065-2071, 2015.
27. G. Lv and **R. Gregg**, "Orthotic Body-Weight Support Through Underactuated Potential Energy Shaping with Contact Constraints," in *IEEE Conf Decision and Control*, Osaka, Japan, pp. 1483-1490, 2015. **Best Student Paper Award**.
28. D. Quintero, A. Martin, and **R. Gregg**, "Unifying the Gait Cycle in the Control of a Powered Prosthetic Leg," in *IEEE Int Conf Rehabilitation Robotics*, Singapore, pp. 289-294, 2015.
29. A. Martin and **R. Gregg**, "Hybrid Invariance and Stability of a Feedback Linearizing Controller for Powered Prostheses," in *Amer Control Conf*, pp. 4670-4676, 2015.
30. A. Nanjangud and **R. Gregg**, "Simultaneous Control of Virtual Constraints for Ankle-Foot Prostheses," in *ASME Dynamic Systems & Control Conf* (Invited Session on Physical Human-Robot Interactions), San Antonio, TX, pp. V001T04A001, 2014.
31. D. Villarreal and **R. Gregg**, "A Survey of Phase Variable Candidates of Human Locomotion," in *IEEE Eng Medicine & Biology Conf*, Chicago, IL, pp. 4017-4021, 2014.
32. A. Nanjangud and **R. Gregg**, "Simultaneous Control of the Compass-Gait Biped for Maintaining Symmetric Gait Across All Mass Ratios," in *American Control Conf*, Portland, OR, pp. 5490-5495, 2014.
33. **R. Gregg**, T. Lenzi, N. Fey, L. Hargrove, and J. Sensinger, "Experimental Effective Shape Control of a Powered Transfemoral Prosthesis," in *IEEE Int Conf Rehabilitation Robotics*, Seattle, WA, 2013.
34. **R. Gregg** and J. Sensinger, "Biomimetic Virtual Constraint Control of a Transfemoral Powered Prosthetic Leg," in *American Control Conf*, Washington, DC, pp. 5702-5708, 2013.
35. **R. Gregg** and U. Topcu, "Towards Formal Verification Methods for Robotic Lower-Limb Prostheses and Orthoses," in the Medical Cyber Physical Systems Workshop, *CPS Week*, Philadelphia, PA, 2013.
36. N. Rosa, A. Barber, **R. Gregg**, K. Lynch, "Stable Open-Loop Brachiation on a Vertical Wall," in *IEEE Int Conf Robotics & Automation*, St. Paul, MN, pp. 1193-1199, 2012.
37. **R. Gregg**, Y. Dhaher, and K. Lynch, "Functional Asymmetry in a Five-Link 3D Bipedal Walker," in *IEEE Eng Med & Bio Conf*, Boston, MA, pp. 7820-7823, 2011.
38. **R. Gregg**, "Controlled Reduction of a Five-Link 3D Biped with Unactuated Yaw," in *IEEE Conf Decision & Control*, Orlando, FL, pp. 669-674, 2011.

39. A. Long, **R. Gregg**, and K. Lynch, "The Simplest Parkour Model: Experimental Validation and Stability Analysis," in *Int Conf Climbing & Walking Robots*, Paris, France, 2011. **Best Technical Paper Award**.
40. **R. Gregg**, A. Degani, Y. Dhafer, and K. Lynch, "The Basic Mechanics of Bipedal Walking Lead to Asymmetric Behavior," in *IEEE Int Conf Rehab Robotics*, Zurich, Switzerland, 2011.
41. **R. Gregg**, T. Bretl, and M. Spong, "A Control Theoretic Approach to Robot-Assisted Locomotor Therapy," in *IEEE Conf Decision & Control*, Atlanta, GA, pp. 1679-1686, 2010.
42. **R. Gregg**, L. Righetti, J. Buchli, and S. Schaal, "Constrained Accelerations for Controlled Geometric Reduction: Sagittal-plane Decoupling for Bipedal Locomotion," in *IEEE Int Conf Humanoid Robots*, Nashville, TN, 2010.
43. **R. Gregg**, T. Bretl, and M. Spong, "Asymptotically Stable Gait Primitives for Planning Dynamic Bipedal Locomotion in Three Dimensions," in *IEEE Int Conf Robotics & Automation*, Anchorage, AK, pp. 1695–1702, 2010.
44. **R. Gregg** and M. Spong, "Bringing the Compass-Gait Bipedal Walker to Three Dimensions," in *IEEE Int Conf Intelligent Robots & Systems*, St. Louis, MO, pp. 4469–4474, 2009.
45. **R. Gregg** and M. Spong, "Reduction-Based Control of Branched Chains: Application to Three-Dimensional Bipedal Torso Robots," in *IEEE Conf Decision & Control*, Shanghai, China, pp. 8166–8173, 2009.
46. **R. Gregg** and M. Spong, "Reduction-Based Control with Application to 3D Bipedal Walking Robots," in *Amer Control Conf*, Seattle, WA, pp. 880–887, 2008. **Best Student Paper Award** and **O Hugo Schuck Award**.
47. A. Ames, **R. Gregg**, and M. Spong, "A Geometric Approach to Three-Dimensional Hipped Bipedal Robotic Walking," in *IEEE Conf Decision & Control*, New Orleans, LA, pp. 5123–5130, 2007.
48. A. Ames and **R. Gregg**, "Stably Extending Two-Dimensional Bipedal Walking to Three Dimensions," in *American Control Conf*, New York, NY, pp. 2848-2854, 2007.
49. A. Ames, **R. Gregg**, E. Wendel, and S. Sastry, "Towards the Geometric Reduction of Controlled Three-Dimensional Bipedal Robotic Walkers," in *Workshop on Lagrangian & Hamiltonian Methods for Nonlinear Control*, Nagoya, Japan, 2006.
50. A. Ames, H. Zheng, **R. Gregg**, and S. Sastry, "Is there Life after Zeno? Taking Executions past the Breaking (Zeno) Point," in *American Control Conf*, Minneapolis, MN, 2006.

## CONFERENCE ABSTRACTS

1. **R. Gregg**, "Phase-based control of locomotion for high-performance prostheses and orthoses," in *NIH Director's High-Risk High-Reward Research Symp*, Bethesda, MD, 2018.
2. **R. Gregg**, "Continuously parameterizing the timing and task adaptations of human locomotion for the control of powered prosthetic legs," in *World Congress Biomech*, 2018.
3. S. Rezazadeh and **R. Gregg**, "Using holonomic and nonholonomic parameterizations to control powered multi-joint prosthetic legs," in *Dynamic Walking Conf*, 2018.
4. S. Kumar, A. Mohammadi, N. Gans, and **R. Gregg**, "Extremum seeking control for model-free auto-tuning of powered prosthetic legs," in *IEEE Int Conf Robotics & Automation*, 2018.
5. S. Rezazadeh and **R. Gregg**, "Towards a robust control paradigm for steady-state and transient walking with active transfemoral prostheses," in *IEEE Int Conf Intelligent Robots & Systems*, 2017.



6. E. Bolivar, S. Rezazadeh, and **R. Gregg**, “How much energy can really be saved using series elastic actuators?”, in *IEEE Int Conf Intelligent Robots & Systems*, 2017.
7. S. Rezazadeh and **R. Gregg**, “A constructive framework for control of anthropomorphic biped systems,” in *Dynamic Walking Conf*, 2016.
8. A. Martin, D. Villarreal, and **R. Gregg**, “Adding variability to a moderately-complex human walking model,” in *Dynamic Walking Conf*, 2016.
9. A. Martin, D. Villarreal, K. Embry, **R. Gregg**, “Relationship between socket forces and center of pressure location for transfemoral amputees,” in *American Society of Biomech*, 2016.
10. **R. Gregg**, “High-performance control of powered prosthetic legs with human-inspired phase variables,” in *NIH Director’s High-Risk High-Reward Research Symp*, Bethesda, MD, 2015.
11. D. Quintero, A. Martin, and **R. Gregg**, “Giving up the finite state machine in the control of lower-limb wearable robots?”, in Workshop on Rehabilitation Robotics and Human-Robot Interaction, *IEEE Int Conf Robotics & Automation*, Seattle, WA 2015.
12. **R. Gregg**, “Virtual constraint control of a powered prosthetic leg: experiments with transfemoral amputees,” in Dynamic Locomotion Workshop, *Robotics: Science & Systems*, Berkeley, CA, 2014.
13. D. Villarreal and **R. Gregg**, “Phase-based control of locomotion for high-performance prostheses and orthoses,” in *Neural Interfaces Conf*, Dallas, TX, 2014.
14. **R. Gregg**, “Phase-based control of locomotion for high-performance prostheses and orthoses,” in *NIH Director’s High-Risk High-Reward Research Symp*, Bethesda, MD, 2013.
15. **R. Gregg**, E. Rouse, L. Hargrove, and J. Sensinger, “The hypothesis of feedback pattern generation in human locomotion,” in *Dynamic Walking Conf*, Pittsburgh, PA, June 2013.
16. **R. Gregg** and J. Sensinger, “From machine to biomimetic control of powered prosthetic legs,” in *Dynamic Walking Conf*, Pensacola, FL, May 2012.

## BOOK CHAPTERS

1. A. Ames, **R. Gregg**, E. Wendel, and S. Sastry, “On the Geometric Reduction of Controlled Three-Dimensional Bipedal Robotic Walkers,” in *Lagrangian & Hamiltonian Methods for Nonlinear Control*, ser. Lecture Notes in Control and Information Sciences, vol. 366. Nagoya, Japan: Springer, 2007, pp. 183-196.

## UNREFEREED MAGAZINE ARTICLES

1. **R. Gregg**, L. Hargrove, and J. Sensinger, “Challenges for Control Research: Control of Powered Prosthetic Legs,” *The Impact of Control Technology*, 2<sup>nd</sup> ed., T. Samad and A.M. Annaswamy (eds.), IEEE Control Systems Society, 2014, available at [www.ieeecss.org](http://www.ieeecss.org).
2. D. Hoelzle, A. Ford, **R. Gregg**, M. Johnson, and J. Kemmerer, “Symposium on Emerging Topics in Control and Modeling: Biomedical Systems [Conference Reports],” *IEEE Control Systems Magazine*, 30(6): 132-134, 2010.

## PATENTS

1. **R. Gregg** et al., “Powered Knee-Ankle Prosthesis with Torque Dense, Low Ratio Actuation,” U.S. Provisional Patent Application, 2018.

2. D. Quintero, H. Zhu, and **R. Gregg**, “Real-Time Calculation of Electric Motor Torque Based on Analog Electric Current Measurements,” U.S. Provisional Patent Application, 2017.
3. **R. Gregg** et al., “Series Elastic Actuator with Electrically Modulated Stiffness,” U.S. Provisional Patent Application, 2017.
4. **R. Gregg** and G. Lv, “Total Energy Shaping for Task-Invariant Control of Exoskeletons,” U.S. Patent Application, 2018.
5. **R. Gregg** and H. Zhu, “Powered Orthosis with Combined Motor and Gear Technology,” U.S. Patent Application, 2018.
6. **R. Gregg** and H. Zhu, “Lower Limb Powered Orthosis with Low Ratio Actuation,” U.S. Patent Application, 2018.
7. **R. Gregg**, G. Lv, and H. Zhu, “Torque Control Methods for Powered Orthosis,” U.S. Patent Application, Dec 2016.
8. **R. Gregg**, D. Quintero, and A. Martin, “Systems and Methods for Prosthetic Device Control,” U.S. Patent Application, Feb 2016.
9. **R. Gregg** and J. Sensinger, “Effective Shape Controller for Lower Limb,” U.S. Patent Application, May 2014.

## INVITED PRESENTATIONS

1. Graduate Seminar, Mechanical Engineering, Texas A&M University, Nov 2018.
2. Seminar, Burke Neurological Institute / Cornell University, White Plains, NY, Oct 2018.
3. Keynote Speaker, “Continuously parameterizing the timing and task adaptations of human locomotion for the control of powered prosthetic legs,” *World Congress of Biomechanics*, Dublin, Ireland, July 2018.
4. *NIH High-Risk High-Reward Research Symposium*, National Institutes of Health, Bethesda, MD, June 2018.
5. Departmental Seminar, Mechanical Eng, University of North Carolina Charlotte, April 2018.
6. *WearRAcon*, Wearable Robotics Association, Scottsdale, AZ, March 2018.
7. GRASP Seminar, University of Pennsylvania, Philadelphia, PA, February 2018.
8. Controls Seminar, University of Michigan, Ann Arbor, MI, February 2018.
9. Keynote Speaker, “When Will Wearable Robots Enable Mobility in the Home and Community?,” *Bridging the Gap*, School of Occupational Therapy, Texas Woman's University, Denton, TX, Oct 2017.
10. Workshop on Human Movement Understanding for Humanoids and Wearable Robots, *IEEE Int Conf Intelligent Robots & Systems*, Vancouver, Canada, Sept 2017.
11. Workshop on Adaptive Control Methods in Assistive Technologies, *IEEE Int Conf Intelligent Robots & Systems*, Vancouver, Canada, Sept 2017.
12. *Annual Meeting of the Texas Chapter of the American Academy of Orthotists and Prosthetists*, Dallas, TX, Aug 2017.
13. Workshop on the Mechanics of Human Locomotion and the Development of Wearable Robotic Systems, *IEEE Int Conf Robotics & Automation*, Singapore, May 2017.
14. Graduate Seminar, Computer Science & Engineering, Texas A&M University, Feb 2017.
15. Advanced Platform Technology Center Lecture Series, Cleveland Clinic and Cleveland Department of Veteran Affairs, Dec 2016.
16. Departmental Seminar, Applied Physiology & Wellness, Southern Methodist Univ, Nov 2016.
17. Departmental Seminar, Mechanical Engineering, Vanderbilt University, Nov 2016.
18. Workshop on Assistive Robotic Devices for Dynamic Locomotion, *Robotics: Science & Systems*, Ann Arbor, MI, June 2016.

19. BME-RIC Seminar, Rehabilitation Institute of Chicago / Northwestern University, March 2016.
20. *WearRAcon*, Wearable Robotics Association, Phoenix, AZ, February 2016.
21. Robotics Seminar, Mechanical Engineering, Northwestern University, January 2016.
22. Departmental Seminar, Mechanical Engineering, University of Texas, Austin, TX, Sept 2015.
23. Exoskeleton Control Theory Sprint, Special Operations Command (SOCOM), Tampa, FL, July 2015.
24. Departmental Seminar, Mechanical Engineering, University of Washington, Seattle, WA, June 2015.
25. Keynote Speaker, "Innovation in Prosthetic and Orthotic Technology for Improved Healthcare," *Health Research Alliance Meeting* (American Heart Association), Dallas, TX, March 2015.
26. Departmental Seminar, Physical Medicine & Rehabilitation, University of Texas Southwestern Medical Center, Dallas, TX, February 2015.
27. Departmental Seminar, Physical Medicine & Rehabilitation, Children's Medical Center of Dallas, Dallas, TX, January 2015.
28. Departmental Seminar, Aerospace & Mechanical Engineering, University of Notre Dame, Notre Dame, IN, January 2015.
29. Texas Biorobotics Workshop, *ASME Dyn Sys Control Conf*, San Antonio, TX, October 2014.
30. *Burroughs Wellcome Fund Scientific Interfaces Symposium*, San Diego, CA, October 2014.
31. Dynamic Locomotion Workshop, *Robotics: Science & Systems*, Berkeley, CA, July 2014.
32. Keynote Speaker, "Initial Steps from Robot Locomotion to High-Performance Prostheses and Orthoses," *Annual Meeting Texas Assoc Orthotists & Prosthetists*, Dallas, TX, Apr 2014.
33. Departmental Seminar, Mechanical Engineering, Michigan State University, East Lansing, MI, Mar 2014.
34. *Texas Systems Day*, Texas A&M University, College Station, TX, March 2014.
35. Departmental Seminar, Computer Science and Engineering, University of Texas at Arlington, Arlington, TX, February 2014.
36. Departmental Seminar, Electrical and Computer Engineering, University of Illinois at Chicago, Chicago, IL, February 2013.
37. Controls Seminar, Coordinated Science Lab, University of Illinois, Urbana, IL, Feb 2013.
38. Controls Seminar, University of Waterloo, Canada, May 2012.
39. Departmental Seminar, Bioengineering, University of Texas, Dallas, TX, February 2012.
40. Departmental Seminar, Institute of Automatic Control Engineering, Technical University of Munich, Germany, March 2011.
41. Departmental Seminar, Mechanical and Aerospace Engineering, University of Florida, Gainesville, FL, January 2011.
42. *Dynamic Walking Conference*, "Control and Planning with Asymptotically Stable Gait Primitives," Cambridge, MA, July 2010.
43. Workshop on 20 Years of Passivity-Based Control: Theory and Applications, *IEEE Conference on Decision and Control*, Shanghai, China, December 2009.

## **ADVISING AND MENTORING**

### **Research Staff:**

1. Chris Nesler, MS (Northwestern), Research Engineer, 2016-present
2. Emma Reznick, BA (Colorado College), Postbaccalaureate Researcher, 2017-2018
3. Aaron Plauche, MS (UT Dallas), Research Engineer, 2015-16, now at Bastian Robotics
4. Yonatan Chatzinoff, BS (UT Dallas), Research Engineer, 2014-2015, now at UT Southwestern Medical Center

### **Postdoctoral Fellows:**

1. Siavash Rezazadeh, PhD (University of Alberta), Research Scientist, 2015-present
2. Alireza Mohammadi, PhD (University of Toronto), 2016-2018, now Assistant Professor at University of Michigan--Dearborn
3. Anne Martin, PhD (Notre Dame), 2014-2015, now Assistant Professor at Penn State Univ.
4. Akshay Nanjangud, PhD (UC Davis), 2013-15, now faculty at CMR Institute of Tech, India

### **PhD Students:**

1. Dario Villarreal (PhD-BME 2017), Conacyt Graduate Fellow, Dissertation: *Investigations of a Unified Phase Variable in Human Locomotion for Applications in Powered Prostheses*, now Assistant Professor at Southern Methodist University
2. Ge Lv (PhD-EE 2018), Louis Beecherl Jr. Graduate Fellow, Dissertation: *Energy Shaping Control of Powered Lower-Limb Exoskeletons for Assistance of Human Locomotion*, now Postdoc at Carnegie Mellon University
3. David Quintero (PhD-ME 2018), Excellence in Education Fellow, Dissertation: *Virtual Constraint Control of Powered Prosthetic Legs: Unifying the Gait Cycle*, now Assistant Professor at San Francisco State University
4. David Allen (ME), Excellence in Education Fellow, 2014-present (joint with Prof. Walter Voit)
5. Edgar Bolivar (ME), 2014-present
6. Nikhil Divekar (BME), Jonsson Family Graduate Fellow, 2017-present
7. Toby Elery (ME), 2014-present
8. Kyle Embry (ME), Excellence in Education Fellow, 2014-present
9. Jonathan Horn (ME), 2017-present
10. Saurav Kumar (EE), 2016-present (joint with Prof. Nicholas Gans)
11. Jianping Lin (ME), 2018-present
12. Emma Reznick (BME), 2018-present
13. Mohammad Taha Ahmad (EE), 2018-present
14. Mark Yeatman (ME), 2016-present
15. Hanqi Zhu (EE), McDermott Graduate Fellow, 2013-present

### **MS Thesis Students:**

1. Aaron Plauché (ME), Thesis: *A Haptic Feedback System for Phase-Based Sensory Restoration in Above-Knee Prosthetic Leg Users*, 2015, now at Bastian Robotics
2. Christopher Harris (ME), 2017-present

### **Undergraduate Research Awardees:**

1. Sara Borboa (BS-ME), 2018 Clark Scholar
2. Maaz Mian (BS-BME), 2018 Clark Scholar
3. Mira Jambusaria (BS-ECE), 2017 National Merit LEADER Scholar
4. Maximillian Virani (BS-BME), 2017 National Merit LEADER Scholar
5. Caleb Ho (BS-ME), 2017 Clark Scholar
6. Zelig Barber (BS-BME), 2016 Clark Scholar
7. Jack Doan (BS-ECE), 2016 UTD Award, now at Rockwell Collins
8. Rebecca Macaluso (BS-BME), 2015 and 2016 UTD Award, now M.S. student at University of Rochester
9. Daniel Lambert (BS-ECE), 2015 UTD Award and Fall 2016 ECS Award
10. Calvin Stence (BS-ME), 2015 Clark Scholar and Spring 2016 ECS Award
11. Rafi Ayub (BS-BME), 2014 UTD Award, now Ph.D. student at Stanford with NSF GRFP
12. Toby Elery (BS-ME), 2014 ECS Award
13. Pritam Shah (BS-ME), 2013 UTD Award

### Undergraduate Senior Design Teams:

1. Orthosis and Prosthesis Testing Device, sponsor: UTSW Medical Center, 2017-18
2. Enhanced Design of Robotic Leg, sponsor: UTD Locomotor Control Systems Lab, 2017-18
3. Wearable Ankle Orthosis, sponsor: Texas Instruments, 2015-2016
4. Multi-Degree-of-Freedom Ankle-Foot Orthosis, sponsor: UTSW Medical Center, 2015-2016
5. Wearable Rehabilitation Sensor, sponsor: UTSW/Rithmio, 2014-15 (**1<sup>st</sup> place project**)
6. Amputee Gait Hip Simulator, sponsor: UTD Locomotor Control Systems Lab, 2014-15
7. Cable-Driven Perturbation Mechanism, sponsor: UTSW Medical Center, 2014
8. Powered Transfemoral Prosthetic Leg, sponsor: UTD Locomotor Control Systems Lab, 2014
9. Upper Limb Prosthetic Simulator, sponsor: UTSW Medical Center, 2013

### TEACHING EXPERIENCE

**Instructor**, University of Texas at Dallas 2013 – Present  
MECH 4310: Systems and Controls (Undergrad) Sp18  
BMEN 4310: Feedback Systems in Biomedical Engineering (Undergrad) Fa15, Fa17, Fa18  
BMEN 6372: Engineering Systems Modeling & Simulation (Graduate) Sp15, Sp16, Sp17  
MECH/EECS 6324: Robot Control (Graduate) Fa14, Fa16  
MECH 2330: Dynamics (Undergrad) Fa13

**Co-Instructor**, Elgersburg School on Nonlinear Control (short course) Spring 2011  
Institut für Mathematik, Technical University Ilmaneu, Elgersburg, Germany

**Graduate Teaching Assistant**, Introduction to Robotics Fall 2008  
University of Illinois, Urbana, IL

### SCHOLARLY REVIEW

**Review Panelist** 2014 – Present  
NIH Musculoskeletal, Oral, and Skin Sciences: ZRG1 MOSS-D82 (2019)  
National Science Foundation (2014, 2016-17)  
National Institutes of Health (2014-15)

**Associate Editor**, *IEEE Transactions on Robotics* Oct 2015 – Present

**Conference Editorial Board Member**, IEEE Control Systems Society 2015 – 2018

**Associate Editor (Conferences)** 2013 – Present  
*IEEE/ASME American Control Conf* (2014-18), *IEEE Conf Control Tech & Applications* (2017),  
*IEEE Conf Decision & Control* (2016-18), *IEEE Int Conf Robotics & Automation* (2014-18), *IEEE Int Conf Intelligent Robots & Systems* (2013, 2015), *ASME Dyn Sys Control Conf* (2014-15)

**Journal Reviewer** 2007 – Present  
*Annals Biomed Eng*, *ASME J Applied Mechanics Reviews*, *ASME J Biomech Eng*, *ASME J Dyn Sys Meas Control*, *ASME J Mech Design*, *ASME J Med Devices*, *Automatica*, *Frontiers in Neurorobotics*, *Frontiers in Neuroscience*, *IEEE Access*, *IEEE Control Systems Mag*, *IEEE Robotics Automation Mag*, *IEEE Trans Automat Control*, *IEEE Trans Autom Sci & Eng*, *IEEE Trans Biomed Eng*, *IEEE Trans Control Sys Tech*, *IEEE Trans Robotics*, *IEEE Trans Neural*

*Sys Rehab Eng, Int J Robotics Res, J Biomech, J Intelligent Service Robotics, J NeuroEng Rehab, Opt Control App Meth, Physica D: Nonlinear Phenom, PLoS ONE, Robotica*

**Conference Reviewer**

2007 – Present

*Amer Control Conf, ASME Dyn Sys & Control Conf, IEEE Conf Aut Sci & Eng, IEEE Int Conf Biomed Rob & Biomechatron, IEEE Conf Control Tech & App, IEEE Conf Decision & Control, IEEE Conf Robotics Biomimetics, IEEE Int Conf Eng Med Bio Soc, IEEE Int Conf Humanoid Rob, IEEE Int Conf Intelli Rob & Sys, IEEE Int Conf Rehab Rob, IEEE Int Conf Rob & Aut, IEEE Multiconf Sys & Control, IFAC World Congress, Robotics: Sci & Sys*

**SCHOLARLY SERVICE**

**Program Chair**, *IEEE/RSJ Int Conf on Intelligent Robots & Systems*, Dallas, TX 2023

**Workshops Chair**, *IEEE Conference on Control Technology & Applications*, Hawaii 2017

**Invited Session Organizer/Chair**

1. Invited Session on Robotic Locomotion Control, *IEEE Conf Control Tech App*, 2017
2. Invited Session on Control Theory in Legged Locomotion, *American Control Conf*, 2016
3. Invited Session on Rehabilitation Robots, *ASME Dyn Sys Control Conf*, 2015 – 2017
4. Invited Session on Control Theory in Medical Rehabilitation, *American Control Conf*, 2014

**Meeting Participant**

1. National Robotics Initiative Principle Investigator Meeting, Washington, DC, Nov 2016.
2. National Academy of Engineering Workshop on Future of Center-Based, Multidisciplinary Engineering Research, Washington, DC, April 2016.
3. CCC Workshop on the U.S. National Robotics Roadmap, San Francisco, CA, March 2016.
4. U.S. Special Operations Command Exoskeleton Control Theory Sprint, Tampa, FL, 2015.

**Co-Chair/Organizer**, Texas Bio-Robotics Workshop 2014  
*ASME Dynamic Systems & Control Conference*, San Antonio, TX

**Co-Chair**, Technical Committee Manufacturing Automation & Robotic Control 2013 – 2014  
IEEE Control Systems Society

**Co-Chair**, Symposium on Control and Modeling of Biomedical Systems 2010  
University of Illinois, Urbana, IL

**UNIVERSITY SERVICE**

**Committee Member**, University of Texas at Dallas, Richardson, TX 2013 – Present  
*Bioengineering*: Faculty Search (2013-15), Graduate Recruiting (2014-17), Seminars (2016-18)  
*Mechanical Engineering*: Faculty Search (2017-18), Graduate (2013-14), DSC Area (2013--)  
*School of ECS*: Executive Council (2018--)  
*University*: ECS Dean Search (2018--), Campus Accessibility (2018-19), Core Facilities (2015)

**Graduate Representative**, Academic Senate Executive Committee 2008 – 2010  
University of Illinois, Urbana, IL

## **INDUSTRY EXPERIENCE**

<b>Intern</b> , The Boeing Company (Phantom Works)	Summer 2008
<b>Intern</b> , SANYO Technology Center, San Jose, CA	Summer 2006
<b>Intern</b> , Hewlett-Packard OuterBay Technologies, Cupertino, CA	Summer 2004

## **TRAINING AND CERTIFICATIONS**

- Certificate Series in Research Administration, University of Texas at Dallas, 2015
- NIH Responsible Conduct of Research (RCR) Training, Northwestern University, 2011

## **PROFESSIONAL MEMBERSHIPS**

- Senior Member, Institute of Electrical & Electronics Engineers (IEEE)
  - Control Systems Society
  - Robotics & Automation Society