

The Knapsack Problem

Suppose we are planning a hiking trip; and we are, therefore, interested in filling a knapsack with items that are considered necessary for the trip. There are N different item types that are deemed desirable; these could include bottle of water, apple, orange, sandwich, and so forth. Each item type has a given set of two attributes, namely a weight (or volume) and a value that quantifies the level of importance associated with each unit of that type of item. Since the knapsack has a limited weight (or volume) capacity, the problem of interest is to figure out how to load the knapsack with a combination of units of the specified types of items that yields the greatest total value. What we have just described is called the *knapsack problem*.

A large variety of resource allocation problems can be cast in the framework of a knapsack problem. The general idea is to think of the capacity of the knapsack as the available amount of a resource and the item types as activities to which this resource can be allocated. Two quick examples are the allocation of an advertising budget to the promotions of individual products and the allocation of your effort to the preparation of final exams in different subjects.

Formally, suppose we are given the following parameters:

w_k = the weight of each type- k item, for $k = 1, 2, \dots, N$,

r_k = the value associated with each type- k item, for $k = 1, 2, \dots, N$,

c = the weight capacity of the knapsack.

Then, our problem can be formulated as:

$$\begin{array}{ll} \text{Maximize} & \sum_{k=1}^N r_k x_k \\ \text{Subject to:} & \sum_{k=1}^N w_k x_k \leq c, \end{array}$$

where x_1, x_2, \dots, x_N are nonnegative integer-valued decision variables, defined by

x_k = the number of type- k items that are loaded into the knapsack.

Notice that since the x_k 's are integer-valued, what we have is not an ordinary linear program, but rather an *integer program*. Consequently, the Simplex algorithm cannot be applied to solve this problem.

As a simple numerical example, suppose we have: $N = 3$; $w_1 = 3$, $w_2 = 8$, and $w_3 = 5$; $r_1 = 4$, $r_2 = 6$, and $r_3 = 5$; and finally, $c = 8$. Observe that of the three item types, the first type has the greatest value per unit of weight. That is, of the three ratios,

$$\frac{r_1}{w_1} = \frac{4}{3}, \frac{r_2}{w_2} = \frac{6}{8}, \text{ and } \frac{r_3}{w_3} = \frac{5}{5},$$

the first ratio is the greatest. Therefore, it seems natural to attempt to load as many type-1 items as possible into the knapsack. Since the capacity of the knapsack is 8, such an attempt will then result in the loading combination $x_1 = 2$, $x_2 = 0$, and $x_3 = 0$, with a total value of

$$r_1x_1 + r_2x_2 + r_3x_3 = 4 \times 2 + 6 \times 0 + 5 \times 0 = 8.$$

Is this loading combination optimal? The fact that this combination leaves a wasted slack of 2 in the knapsack is discomfoting. Indeed, it turns out that this combination is not optimal; and that the optimal combination is to let $x_1 = 1$, $x_2 = 0$, and $x_3 = 1$, which achieves a total value of 9.

We now describe how to derive the optimal solution of this problem using dynamic programming. As in our solution of the equipment-replacement problem, the solution procedure will be in four steps.

Stages and States

Observe that there is one decision to make for each item type. That is, we can imagine an assignment process in which a sequence of values are specified for the x_k 's, one at a time. It follows that we can define one stage for each item type. Furthermore, it should be clear that this definition of stages is independent of the order in which the item types are listed.

To motivate the definition of states, imagine yourself as a consultant who is hired at the beginning of, say, stage k , where $1 \leq k \leq N$. This means that decisions for item types 1 through $k - 1$ have already been made and these past decisions cannot be retracted; and that you are now in charge of making the remaining decisions for item types k through N . So, the question is: What do I need to know in order to make these remaining decisions? A little bit of reflection should convince you that the answer to this consultant question is: the remaining capacity of the knapsack at the beginning of stage k . We should, therefore, define the remaining capacity as the state.

Optimal-Value Function

As noted before, this will be a simple adaptation of the standard definition. In the language of the present problem, let

$V_k(i)$ = the highest total value that can be achieved from item types k through N , assuming that the knapsack has a remaining capacity of i .

Our goal is to determine $V_1(c)$; in the simple numerical example above, this means that we are interested in $V_1(8)$.

Recurrence Relation

Suppose the values of x_1 through x_{k-1} have all been assigned, and we are ready to make an assignment to x_k ; that is, we are now in stage k . Suppose further that the knapsack at this point has a remaining capacity of i , where $0 \leq i \leq c$; that is, we are in state i . Since each type- k item has a weight of w_k , we cannot assign a value greater than i/w_k to x_k . Moreover, observe that i/w_k is not necessarily an integer. It follows that the feasible range for x_k is $0 \leq x_k \leq \lfloor i/w_k \rfloor$, where the notation $\lfloor x \rfloor$ is, for any given x , defined as the greatest integer less than or equal to x .

For any integer x_k in the range specified above, the immediate one-stage contribution to the total value in the knapsack is given by $r_k x_k$. Observe that as a result of such an assignment, or action, the capacity of the knapsack will be further reduced by $w_k x_k$. It follows that the “new” state at the next stage, namely stage $k + 1$, will be $i - w_k x_k$. Therefore, the best possible “future” contribution to the total value in the knapsack is given by $V_{k+1}(i - w_k x_k)$.

Combining the discussions in the above two paragraphs now yields the following recurrence relation:

$$V_k(i) = \max_{0 \leq x_k \leq \lfloor i/w_k \rfloor} [r_k x_k + V_{k+1}(i - w_k x_k)].$$

With the recurrence relation in place, the final step of the solution procedure consists of the recursive computation of the $V_k(i)$'s.

Computation

We will illustrate the computation with the numerical example specified above. Recall that with three item types, the total number of stages is 3.

There are two ways to specify the boundary condition. The first approach is to imagine a fictitious fourth stage and simply let $V_4(i) = 0$ for any i . This corresponds to the fact that after having assigned a value to every x_k , the remaining capacity in the knapsack, if any, will no longer have any potential value. The second approach, of course, is to begin the iterations from stage 3. Since there is little difference between these two approaches, we will adopt the second approach.

Since the specified capacity of the knapsack is 8, the highest possible state in any stage is 8. Suppose we are now in stage 3, which means that we are considering an allocation of type-3 items. The fact that every type-3 item has a weight of 5 implies that the state, or the remaining capacity of the knapsack, must be at least 5 to make a positive assignment to x_3 feasible. It follows that $V_3(0) = V_3(1) = V_3(2) = V_3(3) = V_3(4) = 0$. Next, a similar argument shows that for any state between 5 and 9, there is only enough capacity to accommodate a single type-3 item. Since $r_3 = 5$, this implies that $V_3(5) = V_3(6) = V_3(7) = V_3(8) = 5$. In summary, the boundary condition for our problem is given by the table below.

Stage 3:	i	$V_3(i)$	x_3^*
	0	0	0
	1	0	0
	2	0	0
	3	0	0
	4	0	0
	5	5	1
	6	5	1
	7	5	1
	8	5	1

Note that the last column lists the optimal allocation, denoted by x_3^* , for every state in stage 3.

We now consider stage 2. Since every type-2 item has a weight of 8, the state, or the remaining capacity of the knapsack, must be at least 8 to make a positive assignment to x_2 feasible. Therefore, for any i from 0 through 7, the recurrence relation evaluates to

$$\begin{aligned}
 V_2(i) &= \max_{0 \leq x_2 \leq 0} [r_2 x_2 + V_3(i - w_2 x_2)] \\
 &= 6 \times 0 + V_3(i - 8 \times 0) \\
 &= 0 + V_3(i),
 \end{aligned}$$

where $V_3(i)$ is given in the previous table; and for state 8, where x_2 can be either 0 or 1, the recurrence relation evaluates to

$$\begin{aligned}
 V_2(8) &= \max_{0 \leq x_2 \leq 1} [r_2 x_2 + V_3(8 - w_2 x_2)] \\
 &= \max [6 \times 0 + V_3(8 - 8 \times 0), 6 \times 1 + V_3(8 - 8 \times 1)] \\
 &= \max [0 + V_3(8), 6 + V_3(0)] \\
 &= \max [0 + 5, 6 + 0] \\
 &= 6.
 \end{aligned}$$

These calculations are summarized in the stage-2 table below.

Stage 2: i	Actions		$V_2(i)$	x_2^*
	$x_2 = 0$	$x_2 = 1$		
0	0 + 0	–	0	0
1	0 + 0	–	0	0
2	0 + 0	–	0	0
3	0 + 0	–	0	0
4	0 + 0	–	0	0
5	0 + 5	–	5	0
6	0 + 5	–	5	0
7	0 + 5	–	5	0
8	0 + 5	6 + 0	6	1

(The dashes in the $x_2 = 1$ column indicate the infeasibility of that action.)

Finally, in stage 1, the only state is 8. Since $\lfloor 8/w_1 \rfloor = \lfloor 8/3 \rfloor = 2$, it is feasible to allocate 0, 1, or 2 type-1 items. Therefore, the recurrence relation evaluates to

$$\begin{aligned}
 V_1(8) &= \max_{0 \leq x_2 \leq 2} [r_1 x_1 + V_2(8 - w_1 x_1)] \\
 &= \max [4 \times 0 + V_2(8 - 3 \times 0), 4 \times 1 + V_2(8 - 3 \times 1), 4 \times 2 + V_2(8 - 3 \times 2)] \\
 &= \max [0 + V_2(8), 4 + V_2(5), 8 + V_2(2)] \\
 &= \max [0 + 6, 4 + 5, 8 + 0] \\
 &= 9.
 \end{aligned}$$

These calculations are summarized in the table below.

Stage 1: i	Actions			$V_1(i)$	x_1^*
	$x_1 = 0$	$x_1 = 1$	$x_1 = 2$		
8	0 + 6	4 + 5	8 + 0	9	1

Since $V_1(8) = 9$, we conclude that the highest total value the knapsack can hold is 9.

As in previous examples, the sequence of optimal actions can be read from the above tables sequentially. From the stage-1 table, we have $x_1^* = 1$. With $x_1^* = 1$, the remaining capacity, or the state, at stage 2 will be $8 - 3 \times 1 = 5$; therefore, from the row with $i = 5$ in the stage-2 table, we pick up $x_2^* = 0$. This, in turn, implies that the remaining capacity, or the state, at stage 3 will be $5 - 8 \times 0 = 5$; and a reading of the row with $i = 5$ in the stage-3 table shows that $x_3^* = 1$. Thus, the optimal policy prescribes a knapsack that is loaded with one type-1 item, no type-2 item, and one type-3 item. This completes the solution of the numerical example.

Discussion

If the integrality requirement on the x_k 's are relaxed, then the optimal solution is to load $c/w_1 = 8/3$ units of type-1 items into the knapsack. This is a consequence of the fact that type-1 items have the greatest value per unit of weight.

If the value of the x_k 's are restricted to either 0 or 1, then the resulting problem is called a 0-1 knapsack problem. Such a problem could arise, for example, in the selection of members for a committee (where the value of each x_k corresponds to the exclusion or inclusion of a particular individual).

The recursive computation above can also be carried out via a network representation, in a manner similar to what was done for the equipment-replacement problem. The idea, again, is to represent each stage and state combination as a node embedded in the two-dimensional coordinate system, and to represent each action as an arc. Thus, state 8 in stage 1, for example, will be represented by a node at $(1, 8)$; and the feasible values for x_1 at state 8 in stage 1 will be represented by three arcs that connect $(1, 8)$ with $(2, 8)$, $(2, 5)$, and $(2, 2)$, respectively. Moreover, the one-stage "returns" associated with these three actions, namely 0, 4, and 8, can be thought of as the travel distances from $(1, 8)$ to $(2, 8)$, $(2, 5)$, and $(2, 2)$, respectively. It follows that our problem is equivalent to that of finding the *longest* path between node $(1, 8)$ and any of the nodes $(3, 8)$, $(3, 5)$, $(3, 2)$, and $(3, 0)$ (which have "terminal distances" 5, 5, 0, and 0, respectively) in the resulting network. The calculations are worked out in Figure DP-6. You should verify that the optimal values in Figure DP-6 are identical to those presented in the series of tables above.

The network representation in Figure DP-6 also reveals that not all states in stages 2 and 3 are needed in the recursive computation. Specifically, only $V_2(2)$, $V_2(5)$, and $V_2(8)$ are necessary for stage 2; and only $V_3(0)$, $V_3(2)$, $V_3(5)$, and $V_3(8)$ are necessary for stage 3.

Our dynamic-programming formulation can be easily adapted to solve more general knapsack (or resource allocation) problems of the form:

$$\begin{array}{ll} \text{Maximize} & \sum_{k=1}^N r_k(x_k) \\ \text{Subject to:} & \sum_{k=1}^N w_k(x_k) \leq c, \end{array}$$

where the $r_k(\cdot)$'s and the $w_k(\cdot)$'s are arbitrary functions and the x_k 's are nonnegative integers. That is, the total value and the total weight associated with x_k type- k items do not have to be linear in x_k .

Another generalization is to allow each item type to have both a weight and a volume. More specifically, let v_k be the volume of each type- k item; and suppose that the knapsack has a weight capacity of c_w and a volume capacity of c_v . Then, our problem generalizes to:

$$\begin{array}{ll} \text{Maximize} & \sum_{k=1}^N r_k x_k \\ \text{Subject to:} & \sum_{k=1}^N w_k x_k \leq c_w \\ & \sum_{k=1}^N v_k x_k \leq c_v, \end{array}$$

where the x_k 's are nonnegative integers. Our dynamic-programming formulation can, again, be adapted to solve this problem. The idea is to revise the state definition to a pair of remaining capacities, one in weight and the other in volume. We omit the details. (Example 5 in Chapter 10 of our text has a similar spirit.)

Finally, we note that there exist other dynamic-programming formulations for the knapsack problem. One interesting approach is to imagine loading one item at a time, with the choice of item type being the decision variable. In other words, the loading of an item into the knapsack is considered a stage, and the selection of a particular item type for loading is considered an action. (The total number of necessary stages is not known a priori, however.) The state definition will continue to be the remaining capacity of the knapsack; and the construction of the recurrence relation will be based on the idea of relating the optimal value of a knapsack problem with a given state (or a given remaining capacity) to those of knapsack problems with smaller states (or smaller capacities). This is done as follows. Let

$V(i)$ = the highest total value that can be achieved from a knapsack with capacity i .

(Note that we do not index the stages here, as this information plays no role in this formulation.) Observe that if a type- k item is selected for loading, then the given capacity i will be reduced to $i - w_k$, provided that $i - w_k$ is nonnegative. Moreover, since the immediate contribution from a type- k item to the overall value is r_k and since we should proceed optimally from the new state $i - w_k$ onward, the total value associated with such an action is equal to $r_k + V(i - w_k)$. It follows that the recurrence relation is

$$V(i) = \max_k [r_k + V(i - w_k)],$$

where the values of k are limited to those such that $i - w_k \geq 0$ (if $i - w_k < 0$ for all k , then $V(i)$ equals 0, since no item can be loaded). The boundary condition for this recursion is

simply $V(0) = 0$. For our numerical example above, repeated applications of this recurrence relation yield:

$$V(1) = V(2) = 0,$$

$$V(3) = r_1 + V(0) = 4,$$

$$V(4) = r_1 + V(1) = 4,$$

$$V(5) = \max[r_1 + V(2), r_3 + V(0)] = \max[4 + 0, 5 + 0] = 5,$$

$$V(6) = \max[r_1 + V(3), r_3 + V(1)] = \max[4 + 4, 5 + 0] = 8,$$

$$V(7) = \max[r_1 + V(4), r_3 + V(2)] = \max[4 + 4, 5 + 0] = 8,$$

and finally

$$V(8) = \max[r_1 + V(5), r_2 + V(0), r_3 + V(3)] = \max[4 + 5, 6 + 0, 5 + 4] = 9.$$

Thus, the optimal value is 9, which is in agreement with the earlier solution. There are two optimal loading sequences: a type-1 item and then a type-3 item or a type-3 item and then a type-1 item.