

Instructions: You may not use notes or books on this exam. Don't spend too much time on any one problem. Show your work!

NAME:

1	/10	2	/20	3	/9	4	/12
5	/9	6	/15	7	/10	T	/85

[10 pts](1a) For which numbers b is the matrix

$$A = \begin{bmatrix} 1 & b \\ b & 9 \end{bmatrix}$$

symmetric positive definite?

All upper left submatrices must have positive determinants, $1 > 0$.

$$(1 \times 9) - b^2 > 0 \Rightarrow 9 - b^2 > 0 \Rightarrow 9 > b^2 \Rightarrow \boxed{|b| < 3}$$

(b) If $b = 2$ in the matrix above, find the Cholesky factor R in the decomposition $A = R^t R$.

$$A = \begin{bmatrix} 1 & 2 \\ 2 & 9 \end{bmatrix}$$

$$\boxed{R = \begin{bmatrix} 1 & 2 \\ 0 & \sqrt{5} \end{bmatrix}}$$

check: $R^t R = \begin{bmatrix} 1 & 0 \\ 2 & \sqrt{5} \end{bmatrix} \begin{bmatrix} 1 & 2 \\ 0 & \sqrt{5} \end{bmatrix} = \begin{bmatrix} 1 & 2 \\ 2 & 9 \end{bmatrix} \checkmark$

[20 pts](2) Let

$$A = \begin{bmatrix} 1 & 1000 \\ 0 & 1 \end{bmatrix}.$$

(a) Calculate A^{-1} and the condition number $k_{\infty}(A)$.

$$A^{-1} = \begin{bmatrix} 1 & -1000 \\ 0 & 1 \end{bmatrix}$$

$$\|A\|_{\infty} = \max \text{ row sum}(A)$$

$$\text{so } \|A\|_{\infty} = 1001$$

$$\|A^{-1}\|_{\infty} = 1001$$

$$K_{\infty}(A) = (1001)^2 = 1,002,001$$

$$\text{so } K_{\infty}(A) \approx 1 \times 10^6$$

(b) Find the solution to the system $Ax = b$ for the two right hand sides:

$$b = \begin{bmatrix} 1000 \\ 1 \end{bmatrix}$$

and

$$b + \delta b = \begin{bmatrix} 1000 \\ 0 \end{bmatrix}$$

$$x = \begin{bmatrix} 1 & -1000 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1000 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

$$x + \delta x = \begin{bmatrix} 1 & -1000 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1000 \\ 0 \end{bmatrix} = \begin{bmatrix} 1000 \\ 0 \end{bmatrix}$$

(c) Calculate $\|\delta b\|_\infty / \|b\|_\infty$ and $\|\delta x\|_\infty / \|x\|_\infty$ for the two right hand sides in Part (b) above. Carefully explain Part (b) in light of Part (a).

$$\|f b\|_\infty = \left\| \begin{bmatrix} 0 \\ 1 \end{bmatrix} \right\|_\infty = 1$$

$$\Rightarrow \frac{\|f b\|_\infty}{\|b\|_\infty} = \frac{1}{1000}$$

$$\|b\|_\infty = \left\| \begin{bmatrix} 1000 \\ 1 \end{bmatrix} \right\|_\infty = 1000$$

$$\|f x\|_\infty = \left\| \begin{bmatrix} 1000 \\ -1 \end{bmatrix} \right\|_\infty = 1000$$

$$\Rightarrow \frac{\|f x\|_\infty}{\|x\|_\infty} = 1000$$

$$\|x\|_\infty = \left\| \begin{bmatrix} 0 \\ 1 \end{bmatrix} \right\|_\infty = 1$$

$$\text{So } \frac{\|f x\|}{\|x\|} \leq K(A) \frac{\|f b\|}{\|b\|}$$

$$\Rightarrow 1000 \leq 10^6 (10^{-3}) = 10^3 \checkmark$$

(d) If we solve the system $Ax = b$ using Gaussian Elimination with partial pivoting on a machine with 8 digits of accuracy, what does the condition number in Part (a) tell us about the number of digits we can trust in the solution x ?

$s = 8$ digits accuracy

$$K(A) = 10^6 \Rightarrow 6 = t$$

$s - t$ accurate digits

\Rightarrow we can trust 2 digits in sol'n

[9 pts](3) Show that the following operation in the back substitution algorithm for solving $Rx = b$ is backwards stable:

$$\tilde{x}_1 = b_1 \oslash r_{11}.$$

Specifically you should show that the floating point algorithm gives exactly the right answer to a nearby problem $(R + \delta R)x = b$. (Here \oslash is a floating point divide.)

By the Fundamental Axiom of Floating Point Arithmetic, every floating point arithmetic operation is exact up to a relative error of at most ϵ_{mach} .

So $\tilde{x}_1 = \frac{b_1}{r_{11}} (1 + \epsilon_1)$ where

$|\epsilon_1| \leq \epsilon_{mach}$. We want all the "data perturbations

to occur on the matrix entries of R . So we

a truncated Taylor series approximation to define

$$\epsilon_1' = \frac{-\epsilon_1}{1 + \epsilon_1} \quad \left[\text{Aside: } \frac{1}{1-x} = \sum_{n=0}^{\infty} x^n \quad -1 < x < 1. \text{ If } x = -\epsilon_1 \right.$$

$$\text{then } \sum_{n=0}^{\infty} (-\epsilon_1)^n = \frac{1}{1 + \epsilon_1} \quad \text{or} \quad -\epsilon_1 \sum_{n=0}^{\infty} (-\epsilon_1)^n = \frac{-\epsilon_1}{1 + \epsilon_1} \Rightarrow$$

$$-\epsilon_1 \approx \frac{-\epsilon_1}{1 + \epsilon_1} \equiv \epsilon_1'. \quad \left. \right] \text{ Then } \frac{b_1}{r_{11}} (1 + \epsilon_1) = \frac{b_1}{r_{11} (1 + \epsilon_1)}$$

Please sign the following honor statement: On my honor, I pledge that I have neither given nor received any aid on this exam.

$$= \frac{b_1}{r_{11} \left(\frac{1 + \epsilon_1 - \epsilon_1}{1 + \epsilon_1} \right)} = \frac{b_1}{r_{11} \left(1 - \frac{\epsilon_1}{1 + \epsilon_1} \right)} = \frac{b_1}{r_{11} (1 + \epsilon_1')}$$

So \tilde{x}_1 is exactly the correct solution to the

$$\text{Perturbed Problem } (r_{11} + \delta r_{11}) \tilde{x}_1 = b_1$$

[12 pts] (4) Apply the Gram-Schmidt process to

$$a_1 = \begin{bmatrix} 1 \\ 2 \\ -2 \end{bmatrix}, \quad a_2 = \begin{bmatrix} 1 \\ -1 \\ 4 \end{bmatrix}$$

and write the result in the form $A = QR$.

By Gram-Schmidt, $a = \begin{bmatrix} 1 \\ 2 \\ -2 \end{bmatrix}$ and so

$$f_1 = \frac{a_1}{\|a_1\|} \quad \|a_1\|_2 = \sqrt{1^2 + 2^2 + (-2)^2} = \sqrt{9} = 3$$

$$\text{so } f_1 = \frac{1}{3} \begin{bmatrix} 1 \\ 2 \\ -2 \end{bmatrix} \quad \text{or } f_1 = \begin{bmatrix} 1/3 \\ 2/3 \\ -2/3 \end{bmatrix}$$

$$a_2 = \begin{bmatrix} 1 \\ -1 \\ 4 \end{bmatrix} \quad a_2' = a_2 - (f_1^t a_2) f_1$$

$$(f_1^t a_2) = \begin{bmatrix} 1/3 & 2/3 & -2/3 \end{bmatrix} \begin{bmatrix} 1 \\ -1 \\ 4 \end{bmatrix} = 1/3 - 2/3 - 8/3 = -9/3 = -3$$

$$\text{so } a_2' = \begin{bmatrix} 1 \\ -1 \\ 4 \end{bmatrix} - (-3) \begin{bmatrix} 1/3 \\ 2/3 \\ -2/3 \end{bmatrix} = \begin{bmatrix} 1 \\ -1 \\ 4 \end{bmatrix} + \begin{bmatrix} 1 \\ 2 \\ -2 \end{bmatrix} = \begin{bmatrix} 2 \\ 1 \\ 2 \end{bmatrix}$$

$$\|a_2'\| = \sqrt{2^2 + 1^2 + 2^2} = \sqrt{9} = 3 \quad \text{so } f_2 = \begin{bmatrix} 2/3 \\ 1/3 \\ 2/3 \end{bmatrix}$$

$$Q = \begin{bmatrix} 1/3 & 2/3 \\ 2/3 & 1/3 \\ -2/3 & 2/3 \end{bmatrix}$$

$$R = \begin{bmatrix} f_1^t a_1 & f_1^t a_2 \\ 0 & f_2^t a_2 \end{bmatrix} = \begin{bmatrix} 3 & -3 \\ 0 & 3 \end{bmatrix} = R$$

$$f_1^t a_1 = \begin{bmatrix} 1/3 & 2/3 & -2/3 \end{bmatrix} \begin{bmatrix} 1 \\ 2 \\ -2 \end{bmatrix} = \frac{1}{3} + \frac{4}{3} + \frac{4}{3} = 3 \quad f_2^t a_2 = \begin{bmatrix} 2/3 & 1/3 & 2/3 \end{bmatrix} \begin{bmatrix} 1 \\ -1 \\ 4 \end{bmatrix} = 2/3 - 1/3 + 8/3 = 3$$

[9 pts](5) Solve the least squares problem $Ax = b$ where

$$A = \begin{bmatrix} 1 & 1 \\ 2 & -1 \\ -2 & 4 \end{bmatrix}$$

and

$$b = \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix}$$

using the QR decomposition from the previous problem.

Least Squares for $Ax = b$, use normal eqns

$$A^t A x = A^t b \quad A = QR \Rightarrow (QR)^t (QR)x = (QR)^t b$$

$$\Rightarrow R^t Q^t Q R x = R^t Q^t b \quad Q \text{ orthogonal}$$

$$\Rightarrow R^t R x = R^t Q^t b = \boxed{R x = Q^t b}$$
$$Q^t b = \begin{bmatrix} \frac{1}{3} & \frac{2}{3} & -\frac{2}{3} \\ \frac{2}{3} & \frac{1}{3} & \frac{2}{3} \end{bmatrix} \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

$$R x = Q^t b \Rightarrow \begin{bmatrix} 3 & -3 \\ 0 & 3 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \end{bmatrix} \Rightarrow 3x_2 = 0 \Rightarrow$$

$$x_2 = 0$$

$$3x_1 - 3x_2 = 1 \Rightarrow 3x_1 - 3(0) = 1 \Rightarrow 3x_1 = 1$$

$$x_1 = \frac{1}{3} \text{ so}$$

$$\boxed{\vec{x} = \begin{bmatrix} \frac{1}{3} \\ 0 \end{bmatrix}}$$

[15 pts] (6a) Derive the computational cost of the forward elimination portion of Gaussian Elimination.
 (Note: just stating a final cost without derivation is not sufficient.)

Forward elimination includes division by the pivot to get multiplier and "multiply-subtract" combination. Call each division & each mult-subtraction a single op. 1st eqn of length n takes n operations for every zero we achieve in 1st column. $n-1$ rows underneath the first so first stage of elimination takes $n(n-1) = n^2 - n$ ops. (i.e. all entries in n^2 matrix change except for n in 1st row). When elimination is down to k eqns we need $k^2 - k$ ops. Total ops is $(1^2 + 2^2 + \dots + n^2) - (1 + 2 + \dots + n) = \frac{n(n+1)(2n+1)}{6} - \frac{n(n+1)}{2} = \frac{n^3 - n}{3}$. If n is large count is $\Theta(\frac{n^3}{3})$

(b) Approximately how many total steps does elimination take to solve 10 systems with the same 60×60 coefficient matrix A ?

For forward elimination cost to reduce $A = LU$

$$\text{is } \Theta(n^3) \approx (60^3) = 216,000 \text{ flops}$$

Back substitution is $\Theta(60^2) \approx 10(60^2)$

$$\approx 36,000$$

So total cost to solve 10 systems

$$\text{is about } \begin{array}{r} 216,000 \\ + 36,000 \\ \hline 252,000 \text{ flops} \end{array}$$

[10 pts](7) Prove that

$$\|A\|_1 = \max_{1 \leq j \leq n} \sum_{i=1}^n |a_{ij}|$$

Proof:

$$A = [a_1 | a_2 | \dots | a_n]$$

where each a_j is a column vector of length n .

Unit ball for one norm is set $\{x \in \mathbb{R}^n : \sum_{j=1}^n |x_j| \leq 1\}$

Any vector Ax in image of this set

$$\text{satisfies } \|Ax\|_1 = \left\| \sum_{j=1}^n x_j a_j \right\|_1 \leq \sum_{j=1}^n |x_j| \|a_j\|_1$$

\nearrow linear combination of columns of A \nearrow scalar \nearrow vector

$$\leq \max_{1 \leq j \leq n} \|a_j\|_1 \sum_{j=1}^n |x_j| \leq \max_{1 \leq j \leq n} \|a_j\|_1$$

If $x = e_j$ where j maximizes $\|a_j\|_1$, then

bound is attained and $\|A\|_1 = \max_{1 \leq j \leq n} \|a_j\|_1$

