Effective Generation of Test Sequences for Structural Testing of Concurrent Programs

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Motivation

• Let $P$ be a concurrent program.
• Structural testing of $P$ involves
  – White box-based testing
  – Deriving the reachability graph of $P$
  – Generating a set of test sequences from this graph to satisfy some well-defined coverage criterion
    ➢ all-node criterion
    ➢ all-edge criterion
• In order to reduce testing effort and costs, it is important to reduce the number of test sequences being selected
• Four different methods
  – Two based on *hot spot prioritization*
  – Tow based on *topological sort*
Without losing generality, we only discuss the all-node criterion.

To cover all the edges of a reachability graph, we first generate a dual graph with respect to the original graph such that:

- Each node in the dual graph represents one edge in the original graph.
- Each edge in the dual graph represents one node in the original graph.
- Refer to the figure on the following slide for details.

- A pseudo node H is added to the dual graph as the head of the edge converted from the root of the original graph (s₁ in our case), and
- A pseudo node T is added to the dual graph as the tail of the edge converted from each leaf of the original graph (s₄, s₅, s₆, and s₇ in our case).
- These pseudo nodes will be ignored while generating test sequences to cover all the nodes in the dual graph, i.e., to cover all the edges in the original graph.

Through this conversion, the methods that solve the all-node coverage problem can also be applied to solve the all-edge coverage problem.
All-node versus all-edge/graph versus dual graph (2)

A sample graph (left) and its dual graph (right).

Nodes $T$ and $H$ are "pseudo" nodes in the dual graph.
Two methods $M_1$ and $M_2$ are derived with this strategy.

The major difference between these two methods:
- $M_1$ uses a conservative approach to identify hot spots
- $M_2$ uses an aggressive approach

A hot spot is an uncovered node with the highest composite weight (to be explained) so that covering this node can increase the overall coverage in an efficient way.
Method $M_1$ (1)

- $M_{11}$: Assign a weight to each node.
  - Each node is initially assigned a weight of one.
  - If a node is covered by at least one test sequence, its weight is reassigned to zero.
  - Once a node’s weight becomes zero, it will not be changed again, i.e., once a node is covered, it stays covered.
  - This also implies that every uncovered node has a weight of one and every covered node has a weight of zero.
  - Note that the weights in our graph are associated with nodes instead of edges.
Method $M_1 (2)$

- $M_{12}$: If all the nodes have a weight zero, i.e., every node has been covered, STOP.

- $M_{13}$: Compute the composite weight for each uncovered node.
  - The composite weight of a node is the number of uncovered nodes that are guaranteed to be covered, if this node is covered.
  - This is why we say method $M_1$ uses a conservative approach to identify hot spots.
  - It is the number of uncovered nodes (i.e., nodes whose weight is one) on the shortest path from the root of the graph to the given node.
  - Covered nodes (i.e., nodes whose weight is zero) on this path do not count.
  - The computation can be done by using a modified breadth first search.
Method $M_1 \ (3)$

- $M_{14}$: Identify the hot spot which is the node with the highest composite weight.
  - If there is more than one hot spot, identify (by a random selection) a hot spot which is one of the nodes with the highest composite weight.

- $M_{15}$: **Backtrack** from the hot spot identified at step $M_{14}$ to the root of the graph.
  - In this way, we have selected a path from the root to the hot spot, i.e., a test sequence to cover this hot spot.
  - During the backtracking, a greedy approach is used at each step.
  - For a given hot spot (say $\alpha$), we compare the composite weight of all the uncovered nodes that can go to $\alpha$ in one step, i.e., have an edge from itself to $\alpha$.
    
    - These nodes must be the neighboring nodes of $\alpha$.
    - However, since a reachability graph is a directed graph, not every uncovered neighboring node of $\alpha$ needs to be examined.
Method $M_1$ (4)

- $M_{15}$: (cont’d)
  - Refer to the following reachability graph.
  - The number next to each node is its composite weight.
  - We start from the hot spot $\alpha$. The composite weights of nodes $\sigma$, $\varepsilon$, and $\beta$ (but not $\eta$ or $\omega$) are compared with each other.
  - Since node $\beta$ has the highest composite weight, it is selected as the next node to be back tracked.
  - This implies we are going to select a test sequence covering the hot spot $\alpha$ containing the edge from $\beta$ to $\alpha$ as part of the sequence.

- Mark $\beta$ as covered and change its weight to zero.
- Repeat the same process for $\beta$ to find the next node to be back tracked.
- Continue this process until the root node is reached.
Method \textbf{M}_1 (5)

- \textbf{M}_{16}: Go back to step \textbf{M}_{12}
- After each test sequence is selected, all the nodes on the sequence are marked as \textit{covered} with their weights changed to zero at step \textbf{M}_{15}, and the composite weight of every uncovered node is \textit{recomputed} at step \textbf{M}_{13}.
- As a result, hot spots (i.e., the remaining uncovered nodes with the highest composite weight) move to different locations to provide new guidelines on how to select the next efficient test sequence.
- Finally, every test sequence selected by using the back tracking at step \textbf{M}_{15} is feasible because this is part of the nature of reachability graphs.
Method $M_2(1)$

- The composite weight of a given node in $M_1$ is the number of uncovered nodes on the shortest path from the root of the graph to the node. But, in $M_2$, it is the number of uncovered nodes on the longest path (after the weight negation and possible cycle deletions) from the root to the given node.

- This also implies that $M_1$ uses a conservative approach to identify hot spots, whereas $M_2$ uses an aggressive approach.

- Once again, similar to method $M_1$, the weights in our graph are associated with nodes instead of edges.
Method $M_2 (2)$

- $M_{21}$: This step is the same as step $M_{11}$ except that the initial weight of each node is negative one instead of one.
  - In the negated graph, every uncovered node has a weight of negative one and every covered node has a weight of zero.

- $M_{22}$: If all the nodes have a weight zero, i.e., every node has been covered, STOP.

- $M_{23}$: Use a modified DSP (DAG-SHORTEST-PATHS) algorithm to compute the composite weight for each uncovered node in the corresponding negated acyclic graph.
  - The well-known Dijkstra’s algorithm cannot be used here because it requires all weights to be non-negative which is not the case in method $M_2$. 
Method $M_2$ (3)

- $M_{23}$: (cont’d)
  - The first step in DSP is to conduct a topological sort with respect to all the nodes in the graph. Since this can only be done on acyclic graphs, all the cycles (if any) in the graph have to be removed.
  - We used a “modified” DFS-based algorithm that can not only remove cycles by deleting all the back edges but also return a topological sort of the corresponding acyclic graph.
    - Cycle deletion and topological sort are done simultaneously by using one algorithm.
    - Since the purpose of $M_2$ is to select an efficient set of test sequences to cover all the nodes in a graph, it is all right to remove some back edges in order to break the cycles in the graph.
Method $M_2$ (4)

- $M_{23}$: (cont’d)
  - The composite weight of a given node is the number of uncovered nodes on the shortest path from the root of the negated acyclic graph to the given node.
  - This corresponds to the number of uncovered nodes on the longest path from the root of the “modified” original graph (obtained by deleting all the cycles in the original graph) to the given node.
Method $M_2$ (5)

- $M_{24}$: Find a hot spot. A hot spot is the node whose composite weight has the smallest (negative) value. If there is more than one hot spot, we can randomly select one.

- $M_{25}$: Conduct a back tracking from the hot spot to the root of the negated acyclic graph. The same approach as in $M_{15}$ is also used here.

- $M_{26}$: Go back to step $M_{22}$.
Topological sort-based methods (1)

• A topological sort is used to list all the nodes of a directed acyclic graph in a sequential listing such that if there is an edge from node \( u \) to node \( v \), then \( u \) precedes \( v \) in the listing.
  – If the graph has cycles, these cycles will be deleted as explained in methods \( M_3 \) and \( M_4 \).

• Reverse such a topologically sorted order and make one pass over the nodes in the reversed listing in order to increase the coverage with respect to the all-node criterion in an efficient way.

• The underlying motivation is that a topological sort of a graph can be viewed as an ordering of its nodes along a horizontal line so that all directed edges go from left to right. Covering the nodes in the reversed listing first (i.e., the nodes starting from the right end of original topological listing) has a good chance of selecting a path that covers more nodes. As a result, it is more likely to increase the coverage efficiently.
Two methods $M_3$ and $M_4$ are derived with this strategy

Method $M_3$ uses a BFS-based algorithm, whereas method $M_4$ uses a DFS-based algorithm.
Method $M_3$ \((1)\)

- $M_{31}$: Conduct a BFS-based topological sort to generate a sequential listing of all the nodes.
  - As discussed before, the underlying graph has to be **acyclic**, i.e., all the cycles (if any) in the graph have to be removed.
  - This is done by a “modified” BFS-based algorithm that can not only identify and ignore cycles but also return a topological listing of the corresponding acyclic graph.

- $M_{32}$: **Reverse** the listing obtained at step $M_{32}$.

- $M_{33}$: If the reversed listing is empty, STOP. Otherwise, remove the **first node** from this listing.
  - In the beginning, the reversed listing contains all the nodes in the graph.
Method $M_3 (2)$

- $M_{34}$: Find a path from the root of the graph to the node selected at step $M_{33}$ using a “modified” DFS algorithm.
  - The DFS is modified in a way such that it will check every visited node to see whether it is the target node. If so, the search is terminated. And, we have a test sequence selected for covering the target node.
  - All the nodes in the sequence are marked as “covered” and removed from the remaining listing.

- $M_{35}$: Go back to step $M_{33}$. 
The procedure for $M_4$ is the same as that for $M_3$ except that the topological sort at step $M_{41}$ is a **DFS-based algorithm**, whereas it is a **BFS-based algorithm** at step $M_{31}$. 
Observation (1)

- In $M_1$ and $M_2$, a re-computation of the composite weight for all remaining uncovered nodes is necessary in order to identify a new hot spot every time after the previous hot spot is covered.

- Only one topological sort is needed in $M_3$ and $M_4$ to generate a sequential listing of all the nodes.
For methods $M_1$ and $M_2$, the most expensive step is to compute the composite weights at steps $M_{13}$ and $M_{23}$, respectively.

In the first iteration, the composite weight of every node in the graph needs to be computed because no node has been covered yet. This requires an order of $\Theta(V(V+E))$.

In the subsequent iterations, composite weight is computed only for the remaining uncovered nodes.

Clearly, the number of such uncovered nodes is less than the total number of nodes in the graph.

Hence, the time complexity of each subsequent iteration will not exceed the order of $\Theta(V(V+E))$.

Suppose there are $n$ iterations (i.e., $n$ test sequences to satisfy the all-node or all-edge criterion), the overall run-time complexity for $M_1$ and $M_2$ is $\Theta(nV(V+E))$. 
Run-time complexity for $M_3$ and $M_4$

- For method $M_3$ and $M_4$, the most expensive step is to find a path from the root to a selected node using a “modified” DFS algorithm (refer to step $M_{33}$).

- This implies the run-time complexity for selecting each test sequence is in the order of $\Theta(V+E)$.

- Hence, the overall run-time complexity for $M_3$ and $M_4$ is in the order of $\Theta(n(V+E))$, where $V$ and $E$ are the number of nodes and edges in the graph and $n$ is number of test sequences selected.

- Note that a topological sorting at steps $M_{31}$ and $M_{41}$ requires an order of $\Theta(V+E)$. However, this only needs to be a one-time sorting so it has little impact on the overall run-time complexity.
Space complexity

- Since graphs are saved as adjacency lists, the space required for each method is the same and in the order of $\Theta(V+E)$. 
Case Study

- To demonstrate the effectiveness of our methods, we conducted a case study using reachability graphs generated for five well-known distributed algorithms.
  - le-n: the leader election algorithm where n is the number of processes in the ring
  - tp-n: the token passing algorithm where n is the number of processes in the ring
  - me-n: the mutual exclusion algorithm where n is the number of processes in the network
  - fl-n: the flooding protocol where n is the number of process in the network
  - sw-n: the sliding window protocol where n is the window size

- Reduced reachability graphs of the above algorithms are also constructed.
## Data for the all-node criterion

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<tr>
<th>Reachability Graph</th>
<th>Number of nodes</th>
<th>Number of edges</th>
<th>Number of test cases</th>
<th>The longest test case</th>
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<th>Number of edges</th>
<th>Number of test cases</th>
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</table>
Observation (2)

• In spite of the run-time complexity based on the worst case analysis, all the experiments in our study can find a set of test sequences to cover all the nodes (or edges) in a reasonable time.

• In general, a graph containing more nodes and edges requires more test sequences to cover all the nodes and edges.
  - There are exceptions.
    ➢ Graphs with a linked-list structure only need one test sequence.

• There is no monotonically increasing relation between the number of nodes/edges and the number of test sequences.
  - This is because the number of nodes and edges is not the only factor in deciding how many test sequences are needed to cover all the nodes or all the edges. The structure of the graph also has an important impact.
Observation (3)

- When the graph is small, the number of test sequences needed to cover all the nodes is about the same for every method.

- But, as the size of the graph increases (or more precisely, as the number of nodes and edges increases), the number of test sequences selected by $M_1$ or $M_2$ is smaller than that selected by $M_3$ or $M_4$.

- Such a difference becomes more significant when the graph becomes larger.

- One may argue that this advantage (i.e., smaller number of test sequences) is accompanied by a trade-off in terms of higher run-time complexity for $M_1$ and $M_2$.
  - It is never an issue in our study even for graphs with a few thousand nodes or edges.
  - Of course, this may not always be the case.
  - More studies on the trade-off between run-time complexity and the number of test sequences selected are to be conducted.
In general, the difference in terms of the number of test sequences selected by methods $M_3$ (which uses a BFS-based topological sort) and $M_4$ (which uses a DFS-based topological sort) is small.
- There are exceptions.
**Observation (5)**

- M₃ has all the deepest leaf nodes appear in the beginning of its listing, there is a very good chance that the longest test sequence (i.e., the test sequence with the most number of nodes) is in the first few selected test sequences.
  - For M₃, nodes are covered level-by-level starting from the deepest level, that is, nodes having the largest distance (i.e., largest number of edges) from the root are covered first.

- Some leaf nodes might appear in the middle of the listing generated by using M₄. As a result, it is possible that the longest test sequence so selected is also in the middle of all selected test sequences.

- This information is important because if resources only allow us to select a few test sequences, it is better to select longer test sequences than shorter test sequences. In this regard, M₃ can perform better than M₄ for the graphs used in our study.
To observe how each additional test sequence increases the coverage, we can plot a curve by using the percentage of coverage as the index for the vertical axis and the number of test sequences as the index for the horizontal axis.

- Each curve has a steeper slope in the beginning, implying that coverage increases in a more efficient way with respect to the first few test sequences.

- This is particularly true for $M_1$ and $M_2$.

- In addition, the curves for $M_1$ and $M_2$ have steeper slopes than those for $M_3$ and $M_4$ which implies test sequences selected by the first two methods are more efficient than those by the last methods on increasing the coverage.

- The first “few” test sequences selected by our methods can increase the node and edge coverage in a very significant way.
We present four different test sequence selection methods (two based on hot spot prioritization and two based on topological sort) to effectively select a small set of test sequences to cover all the nodes in a reachability graph.

The same methods can also be used to select test sequences for the all-edge criterion by applying them to the corresponding dual graphs.

Of these methods, $M_1$ and $M_2$ select fewer test sequences than $M_3$ and $M_4$ to achieve 100% node and edge coverage.

- However, $M_1$ and $M_2$ have a higher run-time complexity than $M_3$ and $M_4$.
- For practical applications, the size of the reachability graphs can be very large which may prevent $M_1$ and $M_2$ from being applied.
- Under this condition, $M_3$ and $M_4$ seem to be a more practical choice.
Our data also indicate that the coverage can be increased in a significant way by the first few test sequences selected by our methods.

While the advantage of using a smaller set of test sequences is obvious in terms of management, output verification, etc., it is also important to examine the fault detection effectiveness of these test sequences using real defect data collected in practice.

- Our ongoing research is to apply test sequence selection methods discussed in this presentation to real-life concurrent software and determine how they can help testing practitioners do a better job in finding software bugs.